ON THE DYNAMICS OF A VACCINATION MODEL WITH MULTIPLE TRANSMISSION WAYS

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In this paper, we present a vaccination model with multiple transmission ways and derive the control reproduction number. The stability analysis of both the disease-free and endemic equilibria is carried out, and bifurcation theory is applied to explore a variety of dynamics of this model. In addition, we present numerical simulations to verify the model predictions. Mathematical results suggest that vaccination is helpful for disease control by decreasing the control reproduction number below unity.

Keywords: vaccination model, stability, equilibrium.

1. Introduction

Waterborne diseases, the world's leading killer, are infectious diseases caused by pathogenic microorganisms that are transmitted in contaminated water. According to the World Health Organization (WHO) reports, 3–5 million people are affected by water-related diseases every year. Cholera is an acute intestinal infection caused by bacterium *Vibrio cholerae*; its transmission is different from other diseases since it involves multiple transmission pathways and occurs primarily by drinking contaminated water or eating food that has been contaminated by the feces of an infected person, including one with no apparent symptoms. Currently, cholera is endemic in over 50 countries, including India (2007), Congo (2008), Iraq (2008), Zimbabwe (2008–2009), Vietnam (2009), Kenya (2010), Nigeria (2010), and most recently Haiti (2010–2011) (WHO).

Recently, the use of compartmental models has proved to be a powerful tool for exploring complex transmission dynamics. There have been published many mathematical models focused on modeling and simulating the nature of the cholera dynamics. Capasso and Paveri-Fontana (1979) framed a simple cholera model to study the 1973 cholera epidemic in the European Mediterranean region. Codeço (2001) first proposed an SIRB epidemic model by adding an environmental component into the regular SIR model (B is the *V. cholerae* concentration in the water environment).

The extension of Codeço's model by Hartley *et al.* (2006) accounted for a hyperinfectious state of the pathogen, representing the hyperinfectious state of the pathogen, the explosive infectivity of freshly shed *V. cholerae*, based on the laboratory results. Recently, Liao and Wang (2011) conducted a dynamical analysis of Hartley's model. They studied the stability of both the disease-free and endemic equilibria so as to explore the complex epidemic and endemic dynamics of the disease. Also, Mukandavire *et al.* (2011) considered both human-to-human and environment-to-human transmission pathways and simplified Hartley's model to study the 2008–2009 cholera outbreak in Zimbabwe. Moreover, Tien and Earn (2010) proposed a water-borne disease model with multiple transmission pathways, and identified how these transmission routes influence disease dynamics.

Although waterborne diseases are severe infections, due to vaccination, advanced water treatments and sanitation practices, which shorten the course of the disease and reduce the severity of the symptoms, these terrible diseases are no longer major health threats in most countries. Vaccination of susceptible, as one of the most effective controlling methods for many diseases (measles, pertussis, rubella, hepatitis B, mumps, influenza, etc.) has been included in mathematical compartmental models and published recently. Many studies have shown that vaccination strategies are very important to control or eradicate diseases (Dietz *et al.*, 1985; Kribs-Zaleta and

Velasco-Hernandez, 2000; Kribs-Zaleta and Martcherab, 2002; Brauer, 2004; Samsuzzoha *et al.*, 2012; Szymanska, 2013). Dietz and Schenzle (1985) pointed out that realistic epidemic models need to consider vaccination programmes. Kribs-Zaleta and Velasco-Hernandez (2000) explored disease control via a vaccination program in which the vaccine provides complete protection against low-level infection and partial protection against infection by acute infectives. In the work of Kribs-Zaleta and Martcherab (2002), a simple two-dimensional SIS model with vaccination was exhibited and showed a vaccination campaign meant to reduce a disease's reproduction number below which one may fail to control the disease. Brauer (2004) studied the backward bifurcation in simple vaccination models and gave conditions for the existence of multiple endemic equilibria and backward bifurcations. Samsuzzoha *et al.* (2012) considered an SVEIRS model to explore the impact of vaccination as well as diffusion on the transmission dynamics of influenza. In addition, there are many other epidemic models including different kinds of vaccination (Yildirim and Cherramt, 2009; Song *et al.*, 2009; Yu *et al.*, 2010), such as constant or impulsive.

The aim of this paper is to extend and analyze the waterborne disease model proposed by Tien and Earn (2010) with the inclusion of a vaccinated class, V , and three important factors: vaccination rate ϕ , vaccine efficacy rate σ and waning rate θ . The remainder of the paper is organized as follows. In Section 2, we formulate the vaccination model, and the derivation of the control reproductive number R_C is included. In Section 3, we analyze the vaccination model, study the stability of both the disease-free and endemic equilibria. Section 4 is devoted to the numerical study of the model, which confirms our theoretical results. Finally, we close the paper by a discussion in Section 5.

2. ODE model with vaccination

2.1. ODE model with vaccination and the control reproduction number. Tien and Earn (2010) extended the classical SIR framework by adding a compartment (W) that tracked pathogen concentration in the water. Susceptible individuals are infected with multiple transmission pathways: contact with infected individuals or contact with contaminated water. The corresponding model consists of the following Ordinary Differential Equations (ODEs):

$$\frac{dS}{dt} = \mu N - \beta_W WS - \beta_I SI - \mu S, \quad (1)$$

$$\frac{dI}{dt} = \beta_W WS + \beta_I SI - (\gamma + \mu)I, \quad (2)$$

$$\frac{dR}{dt} = \gamma I - \mu R, \quad (3)$$

$$\frac{dW}{dt} = \alpha I - \xi W, \quad (4)$$

where N is the total population size divided into three groups: S , I and R , denoting the susceptible, the infected and the recovered numbers, respectively. The population size N remains constant, and $S + I + R = N$. Here the parameters β_W and β_I represent the transmission rate for environment-to-human and human-to-human, respectively. Here μ is the natural human birth/death rate, α is the shedding rate, ξ is the bacterial death rate, and γ is the recovery rate.

The basic reproduction number R_0 , which represents the average number of secondary infections that occur when one infective is introduced into a completely susceptible host population (Hethcote, 2000; Van den Driessche and Watraugh, 2002; Vynnycky *et al.*, 2007; Tien and Earn, 2010), is calculated as (Tien and Earn, 2010)

$$R_0 = \frac{N(\beta_W \alpha + \beta_I \xi)}{\xi(\gamma + \mu)}. \quad (5)$$

Based on the above model, we formulate a vaccination model and add a new group V that has begun the vaccination process. Because of the new born and those who have loss of immunity due to earlier infection and vaccination with constant rate ϕ , the number of susceptible individuals is increased. On the other hand, this number is reduced by vaccination, infection and natural death. Moreover, the vaccinated individuals are increased, since the susceptible population is vaccinated and moved to class V , the vaccine has the effect of reducing the infection with constant rate σ , we make the realistic assumption that the vaccine is not totally effective, $0 \leq \sigma \leq 1$, $(1 - \sigma)$ is the vaccine efficacy. Thus, $\sigma = 0$ means that the vaccine is completely effective, $\sigma = 1$ means that the vaccine has no effect. The number of vaccinated individuals is decreased by natural death, while the infection and waning of vaccine induced immunity at the rate θ . The vaccination model is constructed as

$$\frac{dS}{dt} = \mu N - \beta_W WS - \beta_I SI - (\mu + \phi)S + \theta V, \quad (6)$$

$$\frac{dV}{dt} = \phi S - \sigma \beta_I VI - (\mu + \theta)V, \quad (7)$$

$$\frac{dI}{dt} = \beta_W WS + \beta_I SI - (\gamma + \mu)I + \sigma \beta_I VI, \quad (8)$$

$$\frac{dR}{dt} = \gamma I - \mu R, \quad (9)$$

$$\frac{dW}{dt} = \alpha I - \xi W, \quad (10)$$

where S , V , I and R denote the susceptible, the vaccinated, the infected, and the recovered numbers,

respectively. The total population size is $N = S + I + R + V$. Note that in the case of $\sigma = 1$, the vaccine is totally useless. Thus the vaccination model reduces to the vaccination free model (1)–(4).

The solution of the model system (6)–(10) is biologically feasible for all times. Mathematically speaking, the solution domain

$$\bar{D} = \{(S, V, I, R) | S \geq 0, V \geq 0, I \geq 0, R \geq 0, S + V + I + R = N\},$$

is a positively invariant set in $\mathbb{R}^4$.

We can write the ODEs (6)–(10) in vector form:

$$\frac{dX}{dt} = F(X),$$

with

$$X = (S, V, I, R, W)^T.$$

Disease-Free Equilibrium (DFE) points are steady-state solutions where there is no disease. Thus

$$X_0 = \left(\frac{N(\mu + \theta)}{\mu + \phi + \theta}, \frac{N\phi}{\mu + \phi + \theta}, 0, 0, 0 \right)^T. \quad (11)$$

Here, we use the control reproduction number, denoted by R_C , to describe the average number of secondary cases generated by primary cases under specified controls such as vaccination (Anderson and May, 1990; Hethcote, 2000). It is a useful threshold in the study of a disease for predicting a disease outbreak and for evaluating the control strategies. Based on the work of Van den Driessche and Watmough (2000), the next generation operator approach can be used to define the control reproductive number, where $\mathcal{F}$ denotes the rates of the appearance of new infections in each compartment; $\mathcal{V} = \mathcal{V}^+ + \mathcal{V}^-$, $\mathcal{V}^+$ being the vector of individual transfer rates into the particular compartment, and $\mathcal{V}^-$ the vector of individual transfer rates out of the particular compartment.

These two vectors are given by

$$\mathcal{F} = \begin{bmatrix} \beta_W WS + \beta_I SI + \sigma \beta_I VI \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix},$$

$$\mathcal{V} = \begin{bmatrix} (\gamma + \mu)I \\ \xi W - \alpha I \\ \beta_W WS + \beta_I SI + (\mu + \phi)S - \theta V - \mu N \\ \sigma \beta_I VI + (\mu + \theta)V - \phi S \\ \mu R - \gamma I \end{bmatrix}.$$

The next generation matrix is defined as FV^{-1} , where F and V are both the Jacobian matrices given by

$$F = \left[\frac{\partial \mathcal{F}_i}{\partial X_j}(X_0) \right], \quad V = \left[\frac{\partial \mathcal{V}_i}{\partial X_j}(X_0) \right],$$

with $1 \leq i, j \leq 2$. After some algebra, it is found that

$$F = \begin{bmatrix} \beta_I S + \sigma \beta_I V & \beta_W S \\ 0 & 0 \end{bmatrix}$$

and

$$V = \begin{bmatrix} \gamma + \mu & 0 \\ -\alpha & \xi \end{bmatrix}.$$

The next generation matrix, FV^{-1} , has a nonzero eigenvalue corresponding to the spectral radius. It represents the control reproduction number of the model as

$$R_C = \frac{\beta_W \alpha N(\mu + \theta) + \beta_I \xi N(\mu + \theta + \sigma \phi)}{\xi(\gamma + \mu)(\mu + \theta + \phi)}. \quad (12)$$

We consider the vaccination rate ϕ as a key control parameter and other parameters as fixed. R_C depends on the vaccination policy ϕ and it is a decreasing function of ϕ since $R'_C(\phi) \leq 0$. When $\phi = 0$, $R_C = R_0$, and $R_C < R_0$ for all $\phi > 0$ (since $0 \leq \sigma \leq 1$). Thus R_C reflects how the reproduction number becomes smaller under the application of a vaccination control, and shows how much the vaccination reduces R_C .

There is a unique ϕ_C , such that $R_C(\phi_C) = 1$, which can be given as

$$\phi_C = \frac{[\beta_W \alpha N + \beta_I \xi N - \xi(\gamma + \mu)](\mu + \theta)}{\xi(\gamma + \mu) - \beta_I \xi N \sigma}. \quad (13)$$

2.2. Disease-free equilibrium.

Theorem 1. *The disease-free equilibrium of the ODE model (6)–(10) is locally asymptotically stable if $R_C < 1$, and unstable if $R_C > 1$.*

Proof. Since $R_C < 1$, we have

$$N\beta_I(\mu + \theta + \phi\sigma) < (\gamma + \mu)(\phi + \mu + \theta). \quad (14)$$

The Jacobian of the ODE system (6)–(10) is

$$\begin{bmatrix} -\beta_W W - \beta_I I - (\mu + \phi) & \theta & & & \\ \phi & -\sigma \beta_I I - (\mu + \theta) & & & \\ \beta_W W + \beta_I I & \sigma \beta_I I & & & \\ 0 & 0 & & & \\ 0 & 0 & & & \\ -\beta_I S & 0 & -\beta_W S & & \\ -\sigma \beta_I V & 0 & 0 & & \\ \beta_I S - (\gamma + \mu) + \sigma \beta_I V & 0 & \beta_W S & & \\ \gamma & -\mu & 0 & & \\ \alpha & 0 & -\xi & & \end{bmatrix}.$$

After substituting the values for the DFE

$$S = \frac{N(\mu + \theta)}{\mu + \phi + \theta},$$

$$V = \frac{N\phi}{\mu + \phi + \theta},$$

$$I = R = W = 0,$$

the above matrix becomes

$$J_B = \begin{bmatrix} J_{11} & J_{12} \\ J_{21} & J_{22} \end{bmatrix},$$

where

$$J_{11} = \begin{bmatrix} (\mu + \phi) & \theta \\ \phi & -(\mu + \theta) \\ 0 & 0 \\ -\frac{\beta_I N(\mu + \theta)}{\mu + \phi + \theta} \\ -\frac{\sigma \beta_I N\phi}{\mu + \phi + \theta} \\ \frac{\beta_I N(\mu + \theta)}{\mu + \phi + \theta} + \frac{\sigma \beta_I N\phi}{\mu + \phi + \theta} - (\gamma + \mu) \end{bmatrix},$$

$$J_{12} = \begin{bmatrix} 0 & -\frac{\beta_W N(\mu + \theta)}{\mu + \phi + \theta} \\ 0 & 0 \\ 0 & \frac{\beta_W N(\mu + \theta)}{\mu + \phi + \theta} \end{bmatrix},$$

$$J_{21} = \begin{bmatrix} 0 & 0 & \gamma \\ 0 & 0 & \alpha \end{bmatrix},$$

$$J_{22} = \begin{bmatrix} -\mu & 0 \\ 0 & -\xi \end{bmatrix}.$$

The equilibrium is locally asymptotically stable if and only if all the roots of the matrices J_{11} and J_{22} have negative real parts. It is easy to see that the matrix J_{22} has two negative eigenvalues, $(-\mu)$ and $(-\xi)$. After some simple calculation, the two eigenvalues of J_{11} , $(-\mu)$ and $(-\phi - \mu - \theta)$ are clearly negative, and according to the inequality (14), the other eigenvalue of J_{11} , $-(\gamma + \mu)(\phi + \mu + \theta) - N\beta_I(\mu + \theta + \phi\sigma)$ is also negative.

This completes the proof. ■

From the point of view of the control rate ϕ , we can rewrite the Theorem 1 as follows.

Theorem 2. *The disease-free equilibrium of the ODE model (6)–(10) is locally asymptotically stable if $\phi > \phi_C$, and unstable if $\phi < \phi_C$.*

Next, we focus on the global stability of the ODE system (6)–(10) if $R_0 < 1$. We establish the following result.

Theorem 3. *The disease-free equilibrium of the ODE model (6)–(10) is globally asymptotically stable whenever $R_0 < 1$.*

Proof. We can integrate the equations (6)–(9) to obtain

$$S(t) = \int_{-\infty}^t (\mu N - \beta_W W S - \beta_I S I + \theta V) \times e^{-(\mu + \phi)(t-s)} ds, \quad (15)$$

$$V(t) = \int_{-\infty}^t (\phi S - \sigma \beta_I V I) e^{-(\mu + \theta)(t-s)} ds, \quad (16)$$

$$I(t) = \int_{-\infty}^t (\beta_W W S + \beta_I S I + \sigma \beta_I V I) \times e^{-(\gamma + \mu)(t-s)} ds, \quad (17)$$

$$W(t) = \int_{-\infty}^t \alpha I e^{-\xi(t-s)} ds. \quad (18)$$

From Eqn. (18), with the substitution $x = t - s$, it follows that

$$\limsup_{t \rightarrow \infty} W(t) = \limsup_{t \rightarrow \infty} \int_0^\infty (\alpha I(t - x)) e^{-\xi x} dx.$$

Then we apply the following lemma introduced by Kribs-Zaleta (1999).

Lemma 1. (Kribs-Zaleta, 1999) *Given a measurable sequence of non-negative uniformly bounded functions f_n ,*

$$\begin{aligned} \int \liminf f_n &\leq \liminf \int f_n \\ &\leq \limsup \int f_n \leq \int \limsup f_n. \end{aligned}$$

Then Eqn. (19) becomes

$$\begin{aligned} \limsup_{t \rightarrow \infty} W(t) &\leq \int_0^\infty \limsup_{t \rightarrow \infty} \alpha I(t - x) e^{-\xi x} dx \\ &\leq \limsup_{t \rightarrow \infty} \alpha I(t) \int_0^\infty e^{-\xi x} dx \\ &= \frac{\alpha}{\xi} \limsup_{t \rightarrow \infty} I(t). \end{aligned}$$

Similarly, from Eqn. (17) we obtain

$$\begin{aligned} \limsup_{t \rightarrow \infty} I(t) &\leq \limsup_{t \rightarrow \infty} \int_0^\infty [\beta_W W(t-x)N \\ &\quad - V(t-x) + \beta_I I(t-x)N \\ &\quad - \beta_I V(t-x)I(t-x)(1-\sigma)] dx \\ &\leq \limsup_{t \rightarrow \infty} [\beta_W W(t)N + \beta_I I(t)N] \\ &\quad \times \int_0^\infty e^{-\xi x} dx \\ &\leq \frac{(\frac{\alpha}{\xi}N + \beta_I N)}{\gamma + \mu} \limsup_{t \rightarrow \infty} I(t) \\ &= \frac{N(\beta_W \alpha + \beta_I \xi)}{\gamma \xi + \mu \xi} \limsup_{t \rightarrow \infty} I(t). \end{aligned}$$

Since $R_0 < 1$, the inequality is true only if

$$\limsup_{t \rightarrow \infty} I(t) = 0.$$

■

3. Endemic equilibria

Endemic equilibrium points are steady-state solutions where the disease persists in the population (Chitnis *et al.*, 2008). We find that long term behavior has some important epidemiological implications such as whether an outbreak of a disease may result in an endemic situation or the infection will die out. In this section we shall conduct the endemic analysis. By setting the right-hand sides of Eqns. (6)–(10) to zero, endemic equilibria $E = (S^*, V^*, W^*)$ are such that

$$S^* = \frac{(\gamma + \mu)(\sigma \beta_I I^* + \mu + \theta)}{[\phi \sigma \beta_I + (\frac{\beta_W \alpha}{\xi} + \beta_I)(\sigma \beta_I I^* + \mu + \theta)]}, \quad (19)$$

$$V^* = \frac{(\gamma + \mu)\phi}{[\phi \sigma \beta_I + (\frac{\beta_W \alpha}{\xi} + \beta_I)(\sigma \beta_I I^* + \mu + \theta)]}, \quad (20)$$

$$W^* = \frac{\alpha I^*}{\xi}. \quad (21)$$

In addition, we obtain a single quadratic equation for I^* ,

$$A(I^*)^2 + BI^* + C = 0, \quad (22)$$

where

$$A = (\gamma + \mu)(\beta_W \alpha + \beta_I \xi)\sigma \beta_I, \quad (23)$$

$$\begin{aligned} B = & -\mu N(\beta_W \alpha + \beta_I \xi)\sigma \beta_I + \mu \xi(\gamma + \mu)\sigma \beta_I \\ & + (\gamma + \mu)\xi \phi \sigma \beta_I + (\gamma + \mu)(\beta_W \alpha + \beta_I \xi) \\ & \times (\mu + \theta), \end{aligned} \quad (24)$$

$$C = \mu(1 - R_C)\xi(\gamma + \mu)(\mu + \theta + \phi). \quad (25)$$

Note that $A = 0$ if and only if $\sigma = 0$. When $A = 0$, the endemic equilibrium is unique and exists only if $R_C > 1$. In what follows, we must assume that $0 < \sigma < 1$ (consistent with the assumption in Section 2). If $\sigma = 0$, $A = 0$, then $A(I^*)^2 + BI^* + C = 0$ is a linear equation with a unique solution

$$I^{*'} = \frac{(\gamma + \mu)R_C'}{\mu N(R_C' - 1)},$$

where

$$R_C' = \frac{\beta_W \alpha N(\mu + \theta) + \beta_I \xi N(\mu + \theta)}{\xi(\gamma + \mu)(\mu + \theta + \phi)}.$$

Clearly, the sign of C depends on the value of R_C . It is obvious that $A > 0$ since all parameters are positive. The two non-zero roots of Eqn. (22), I_1 and I_2 , must satisfy

$$I_1 I_2 = \frac{C}{A}, \quad I_1 + I_2 = -\frac{B}{A}.$$

When $R_C > 1$, $C < 0$, $B^2 - 4AC > 0$, there is one and only one positive real root. If $R_C < 1$, then $C > 0$, which yields

$$N(\beta_W \alpha + \beta_I \xi) < \xi(\gamma + \mu).$$

Thus

$$\begin{aligned} B = & \mu \sigma \beta_I [\xi(\gamma + \mu) - N(\beta_W \alpha + \beta_I \xi)] \\ & + (\gamma + \mu)\xi \phi \sigma \beta_I + (\gamma + \mu)(\beta_W \alpha + \beta_I \xi) \\ & > 0. \end{aligned}$$

Hence, here we have either two negative real roots, or two complex conjugate roots with negative real parts of Eqn. (22). There is no positive endemic equilibrium.

The Jacobian matrix for the system (6)–(10) is given by

$$\begin{bmatrix} -\beta_W W - \beta_I I - (\mu + \phi) & \theta & & & & & \\ \phi & -\sigma\beta_I I - (\mu + \theta) & & & & & \\ \beta_W W + \beta_I I & \sigma\beta_I I & & & & & \\ 0 & 0 & & & & & \\ 0 & 0 & & & & & \\ -\beta_I S & 0 & -\beta_W S & & & & \\ -\sigma\beta_I V & 0 & 0 & & & & \\ \beta_I S - (\gamma + \mu) + \sigma\beta_I V & 0 & \beta_W S & & & & \\ \gamma & -\mu & 0 & & & & \\ \alpha & 0 & -\xi & & & & \end{bmatrix},$$

where the characteristic polynomial of the matrix J_B^* is found as

$$\det(\lambda I - J_B^*) = (\lambda + \mu) [a_4 \lambda^4 + a_3 \lambda^3 + a_2 \lambda^2 + a_1 \lambda + a_0],$$

whose coefficients a_i in terms of the elements of J_B^* are

$$\begin{aligned} a_4 &= 1, \\ a_3 &= \beta_W W^* + \beta_I I^* + \sigma\beta_I I^* + 2\mu + \phi + \theta + \xi \\ &\quad + (\gamma + \mu - \beta_I S^* - \sigma\beta_I V^*), \\ a_2 &= \xi(\sigma\beta_I I^* + \mu + \theta) + \xi(\beta_W W^* + \beta_I I^* + \mu + \phi) \\ &\quad + (-\beta_I S^* - \sigma\beta_I V^* + \gamma + \mu)(\sigma\beta_I I^* + \mu + \theta) \\ &\quad + (-\beta_I S^* - \sigma\beta_I V^* + \gamma + \mu) \\ &\quad \times (\beta_W W^* + \beta_I I^* + \mu + \phi) \\ &\quad + (\beta_W W^* + \beta_I I^* + \mu)(\sigma\beta_I I^* + \mu + \theta) \\ &\quad + \phi(\sigma\beta_I I^* + \mu) \\ &\quad + \sigma^2 \beta_I^2 V^* I^* + \beta_W W^* + \beta_I I^*, \\ a_1 &= \xi(\beta_W W^* + \beta_I I^* + \mu)(\sigma\beta_I I^* + \mu + \theta) \\ &\quad + [(\beta_W W^* + \beta_I I^* + \mu)(\sigma\beta_I I^* + \mu + \theta) \\ &\quad + \phi(\sigma\beta_I I^* + \mu)] \\ &\quad \times (-\beta_I S^* - \sigma\beta_I V^* + \gamma + \mu) + \xi\phi(\sigma\beta_I I^* + \mu) \\ &\quad + (\sigma\beta_I I^* + \mu + \theta + \xi + \alpha)(\beta_W W^* + \beta_I I^*) \\ &\quad + (\beta_W W^* + \beta_I I^* + \mu + \phi + \xi)\sigma^2 \beta_I^2 V^* I^* \\ &\quad + \phi^2 \beta_I^2 S^* I^*, \\ a_0 &= (\beta_W W^* + \beta_I I^* + \mu + \phi)\xi\sigma^2 \beta_I^2 V^* I^* \\ &\quad + \theta\sigma\beta_I V^*(\beta_W W^* + \beta_I I^*) + \xi\phi^2 \beta_I^2 S^* I^* \\ &\quad + (\xi + \alpha)(\sigma\beta_I I^* + \mu + \theta)(\beta_W W^* + \beta_I I^*) \\ &\quad + \xi\phi(\sigma\beta_I I^* + \mu)(-\beta_I S^* - \sigma\beta_I V^* + \gamma + \mu). \end{aligned}$$

The criterion that provides necessary and sufficient conditions for the endemic equilibrium to be asymptotically stable is the Routh–Hurwitz criterion (Korn *et al.*, 2000), which requires

$$a_3 > 0, \quad a_1 > 0, \quad a_0 > 0, \\ a_1(a_2 a_3 - a_1) > a_0 a_3^2.$$

From Eqn. (8), it is easy to see that

$$\gamma + \mu - \beta_I S - \sigma\beta_I V > 0.$$

Thus $a_3 > 0$, $a_1 > 0$ and $a_0 > 0$.

To prove the inequality $a_1(a_2 a_3 - a_1) > a_0 a_3^2$, it is convenient to prove the following two inequalities:

$$a_1 a_2 a_3 > 2a_1^2, \\ a_1 a_2 a_3 > 2a_0 a_3^2.$$

These inequalities can be verified by direct calculation (details omitted), establishing the following theorem.

Theorem 4. *The positive endemic equilibrium of the ODE system (6)–(10) is locally asymptotically stable if $R_C > 1$.*

In epidemiology, bifurcation theory is concerned with how solutions of a differential equation depend on threshold parameters, and it can explain how the changes in dynamics take place from a resting state to oscillations. It plays a relevant role in disease control and eradication. Next, we show that there are no backward bifurcations possible when $R_C < 1$ and $B > 0$. From $R_C < 1$ it follows that

$$\beta_W \alpha N(\mu + \theta) + \beta_I \xi N(\mu + \theta + \sigma\phi) < \xi(\gamma + \mu)(\mu + \theta + \phi),$$

that is,

$$N(\mu + \theta)(\beta_W \alpha + \beta_I \xi) < \xi(\gamma + \mu)(\mu + \theta + \phi). \quad (26)$$

Substituting this inequality into the expression (25) of B , the first term of B satisfies

$$\mu N(\beta_W \alpha + \beta_I \xi) \sigma \beta_I < \frac{\mu \sigma \beta_I \xi (\gamma + \mu) (\mu + \theta + \phi)}{\mu + \theta} < \mu \sigma \beta_I \xi (\gamma + \mu).$$

The other terms of B are all positive. Thus $B > 0$ whenever $R_C < 1$. Hence, we have a forward bifurcation when $R_C = 1$. This result contrasts with the well-known analysis of some regular SIR epidemic models (Brauer, 2000; Van den Driessche *et al.*, 2000; Kribs-Zaleta and Mertcherab, 2002; Arino *et al.*, 2003; Chitnis *et al.*, 2006).

From this conclusion, when $R_C < 1$, the infectious number decreases to zero. When $R_C > 1$, the infectious number either increases or decreases to the curve that represents the endemic equilibrium which is stable. We can predict that significant changes make oscillations during the long term period.

Theorem 5. *The ODE model system (6)–(10) has a forward bifurcation at $R_C = 1$.*

4. Simulation results

4.1. Vaccination free model. Cholera is one of the worst waterborne diseases and is not easy to control. In order to better understand the serious cholera outbreak as well as for possible prediction and control of future cholera epidemics, we apply the vaccination free model (1)–(4) and the vaccination model (6)–(10) to study the cholera dynamics. As an example, we use the data of the 2008–2009 cholera outbreak in Zimbabwe to verify the models. The Zimbabwe cholera outbreak began in August 2008, swept to all of Zimbabwe's ten provinces, and spread to Botswana, Mozambique, South Africa and Zambia quickly. The case fatality rate for the outbreak was higher than expected for such outbreaks. On 4 December 2008, the Zimbabwe government declared the outbreak to be a national emergency and requested international aid (WHO). The principal cause of the outbreak is the lack of safe water in urban areas and communities. Many places had no water supply for much longer during the outbreak period. By March 2009 the World Health Organization estimated that 4,011 people had succumbed to the waterborne disease and 91,164 cases were infected.

Since β_I and β_W vary from place to place, in our Zimbabwe case we need to adjust these two parameters to match the reported infections data published by the WHO for the period from the end of August 2008 to March, 2009. Since the total population in Zimbabwe is 12,347,240, in order to make the calculation simpler we scale down all data numbers by a factor of 1,200. All epidemiological parameter values for cholera in the literature are given in Table 1. When $\beta_W = 0.00000002$, $\beta_I = 0.0001568$, the model prediction can well fit the

data. After substituting all parameters into Eqn. (5), $R_0 = 1.163$, showing cholera would spread in Zimbabwe. Figure 1 shows the data fitting for the infected population I , where the curve represents the model prediction and the squares mark the reported Zimbabwean data.

To verify the model prediction, we run the numerical simulation for a long time interval. Figures 2 and 3 show the results for I , S and R of the vaccination free model with the initial condition $I(0) = 1$, $S(0) = 9999$, $R(0) = B(0) = 0$. By substituting all parameter values into Eqns. (1)–(4), one can obtain the unique positive endemic equilibrium $(I^*, S^*, R^*) = (0.442, 8699.5, 1300)$. In Fig. 2, cholera outbreak reaches the first peak at $t = 22.5$ weeks with the value 76 (normalized value), then drops to almost zero, which means the disease is gradually eradicated from the population. However, next a smaller peak appears with a smaller value for I as 23 at $t = 325$ weeks, and several oscillations later, showing cholera will restart again and again until I reaches a steady-state value 0.442, and after that no more outbreaks are triggered. Figure 3 shows almost the same trend with different magnitude, susceptible population S and recovered population R appear the first pulse at $t = 22.5$ weeks with peak value around 7,700, and 2,224, respectively. Finally, S and R reach their steady-state value 8699.5 and 1300, respectively.

4.2. Vaccination model. For the vaccination model (6)–(10), since the control reproduction number R_C , which provides useful guidelines for the prevention and

Fig. 1. Figure of I vs. time (weeks) shows data fitting for the cholera outbreak in Zimbabwe, where the curve represents the model prediction and the squares mark the reported data. After normalized by a factor of 1,200, the cholera outbreak had 10, 30, 66 and 76 (normalized) cholera infections after 12 weeks, 18 weeks, 22.5 weeks and 26.5 weeks, respectively, from the beginning of the outbreak.

Table 1. Model parameters and values.

Parameter	Symbol	Value
Natural human birth/death rate	μ	$(35y)^{-1}$
Shedding rate	α	10 cells/ml.day
Bacterial death rate	ξ	$(30d)^{-1}$
Recovery rate	γ	$(5d)^{-1}$
Vaccination rate	ϕ	Variable
Waning rate	θ	Variable
Vaccine efficacy rate	σ	Variable

control strategies on cholera epidemics in Zimbabwe, strongly depends on the parameters $\beta_W, \beta_I, \phi, \sigma$, and θ , in order to determine which of the parameters are most influential on model output, we use the Latin hypercube sampling approach (Blower and Dowlatabadi, 1994; Marino *et al.*, 2008) to incorporate the uncertainty in such five parameters into the model. A sensitive analysis can be performed by calculating Partial Rank Correlation Coefficients (PRCCs) for each parameter. The magnitude of the PRCC indicates the importance of the uncertainty in contributing to the imprecision in predicting the value of the parameters. As shown in Table 2, we pick the total infection I as the outcome and use sample sizes $n = 1000$ and $n = 2000$, respectively. Here β_I and β_W are more sensitive than other parameters. Especially, β_I is

Fig. 2. Result for I vs. time (weeks) of a vaccination free model with the initial condition $I(0) = 1, S(0) = 9999, R(0) = B(0) = 0$.

Fig. 3. Result for S, R vs. time (weeks) of a vaccination free model with the initial condition $I(0) = 1, S(0) = 9999, R(0) = B(0) = 0$.

the most influential parameter in determining R_C .

If we rewrite the expression for R_C as

$$R_C = 1 + \frac{EI^2 + FI}{DI + H}, \quad (27)$$

where

$$\begin{aligned} E &= (\gamma + \mu)(\beta_W \alpha + \beta_I \xi) \sigma \beta_I, \\ F &= [\mu \sigma^2 \beta_I^2 N^2 \xi \phi - \mu N \sigma \beta_I \xi (\gamma + \mu) \phi \\ &\quad + (\gamma + \mu)^2 (\mu + \theta) \xi (\mu + \theta + \phi)] / N (\mu + \theta), \\ H &= \mu \xi (\gamma + \mu) (\mu + \theta + \phi), \end{aligned}$$

then Eqn. (27) represents approximately a curve passing the bifurcation point $R_C = 1$. After substituting all parameters into Eqn. (27) and setting $\phi = 0.5, \sigma = 0.2, \theta = 0.5$, a bifurcation diagram is illustrated in Fig. 4, providing a picture of how these equilibria depend on R_C and how stability exchanges at point $R_C = 1$.

Take the economic reason into consideration. Vaccination strategies cost a lot, so if we want to succeed in vaccinating the disease and bringing the control reproduction number less than one, it is necessary to find the minimum control reproduction number R_C , that is, a certain vaccination rate ϕ^* can reduce R_C to a value which is less than one as σ and θ are fixed. Thus

$$\phi^* > \frac{(\mu + \theta)[\beta_W \alpha N + \beta_I \xi N - \xi(\gamma + \mu)]}{\xi[(\gamma + \mu) - \beta_I N \sigma]}.$$

Table 2. Sensitivity analysis.

	β_W	β_I	ϕ	σ	θ
Prcc Value ($n = 1000$)	0.6298	0.8885	0.3284	0.0558	0.03646
Prcc Value ($n = 2000$)	0.5878	0.8912	0.2109	0.08665	0.07032

Fig. 4. Plot of I vs. R_C shows a forward bifurcation with $\phi = 0.5, \sigma = 0.2, \theta = 0.5$, other parameters being given in Table 1. The solid lines represent the stable equilibria, and the dashed line represents the unstable equilibrium. There is a stability exchange at $R_C = 1$.

Here, we consider the parameter values $\sigma = 0.2$ (vaccine is 80% effective), $\theta = 0.5$, based on (28). We need $\phi > 0.10$, hence $R_C < 1$. As shown in Fig. 5, we set the initial condition as $I(0) = 100$, $V(0) = 100$, $S(0) = 9800$, $R(0) = B(0) = 0$, and choose parameter values $\phi = 0.3$, $\sigma = 0.2$, and $\theta = 0.5$. In this case, $R_C = 0.81$ and the disease quickly dies out ($I = 0$), so that it can be eradicated. It is important to note that since the collapse of Zimbabwe's public health system, hospitals lacked basic medicines and staff, and this vaccination standard was not met in Zimbabwe.

Similarly, we now present numerical simulations in order to verify the vaccination model prediction with the initial condition $I(0) = 1$, $V(0) = 1$, $S(0) = 9998$, $R(0) = B(0) = 0$, and the parameter values $\phi = 0.05$,

Fig. 5. Result for I vs. time (weeks) with the initial condition $I(0) = 100$, $V(0) = 100$, $S(0) = 9800$, $R(0) = B(0) = 0$, parameter values $\phi = 0.3$, $\sigma = 0.2$, and $\theta = 0.5$.

Fig. 6. Result for I vs. time (weeks) with the initial condition $I(0) = 1$, $V(0) = 1$, $S(0) = 9998$, $R(0) = B(0) = 0$, parameter values $\phi = 0.05$, $\sigma = 0.2$, and $\theta = 0.5$.

$\sigma = 0.2$, $\theta = 0.5$. Under this setting, $R_C = 1.08$. Figure 6 shows the cholera outbreak will be triggered with a peak value around 15, which is much lower than that of the vaccination free model, showing the vaccination strategies do weaken the cholera outbreak even though they do not eradicate the outbreak. If we consider a much more longer period, a single positive endemic equilibrium exists, $(I^*, V^*, S^*, R^*) = (0.2263, 843.2, 8439.8, 716.78)$. As shown in Figs. 7 and 8, after the first outbreak with a lower magnitude, there exist several oscillations until I drops to 0.2263. V , S and R reach their steady-state values at 843.2, 8439.8, 716.78, respectively. Thus, our vaccination model predicts that, even with the vaccination, and if $\phi < \phi^*$, there will be a cholera outbreak every 70 years in Zimbabwe, and that the disease will remain endemic in the long term finally.

5. Conclusion

We presented a vaccination model (6)–(10) for the transmission of cholera, with multiple transmission pathways: direct human-to-human and indirect water-to-human modes, which differentiate cholera from many other infectious diseases. The basic reproduction number as modified by vaccination, namely, control reproduction number R_C is derived by (12) using the next generation matrix method. It is a key parameter in our model. We showed that if R_C is less than one, the disease dies out and the disease-free equilibrium is stable. If R_C is greater than one, the disease persists and the disease free equilibrium is unstable while the positive endemic equilibrium is stable. The forward bifurcation occurs at the critical point $R_C = 1$ (see Fig. 4).

We have to note that it is generally difficult to show the global stability for the endemic equilibrium

Fig. 7. Infected population I vs. time (weeks) of a vaccination model with the initial condition $I(0) = 1$, $V(0) = 1$, $S(0) = 9998$, $R(0) = B(0) = 0$.

for high-dimensional nonlinear systems, such as our vaccination model (6)–(10), no matter which methods we use—the classic Lyapunov functions or the classical Poincaré–Bendixson framework, the theory of monotone flows–Lipschitz manifolds, etc. (Moghadas and Gumel, 2002; Zhang and Ma, 2003; Li and Zhen, 2005). Recently, a few efforts (Feckan, 2001; Sanchez, 2010) provide useful directions for our future work to study the global stability for high-dimensional models. We only present the graph trajectory of S vs. I in Fig. 9 with three different initial conditions, and one can see that the endemic equilibrium seems to be globally stable if $R_C > 1$.

We must point out that vaccination is not the only control measure against a cholera outbreak. Water sanitation, medical therapy and antibiotic treatment are possible prevention and intervention strategies. Also, the vaccination does not always work out due to the limitations of the medical development level and financial budget, which is also a restriction in our study. However, it is not possible to extend this vaccination model to other kinds of diseases, such as HIV, since there is no vaccine for HIV yet (Gani *et al.*, 1997). Moreover, in this paper, we consider the vaccination as a continuous state, since sometimes the vaccination process is discontinuous or seasonal, it can be modeled by impulsive differential equations, which is one of our future works.

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Fig. 8. Result for S , R , V vs. time (weeks) of a vaccination model with the initial condition $I(0) = 1$, $V(0) = 1$, $S(0) = 9998$, $R(0) = B(0) = 0$.

Fig. 9. Endemic equilibrium point of I vs. S with three different initial conditions: $I_1 = 1$ (a), $I_2 = 100$ (b), $I_3 = 200$ (c).

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