

SETS OF BOUNDED REMAINDER FOR THE BILLIARD ON A SQUARE

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ABSTRACT. We study sets of bounded remainder for the billiard on the unit square. In particular, we note that every convex set S whose boundary is twice continuously differentiable with positive curvature at every point, is a bounded remainder set for almost all starting angles α and every starting point \mathbf{x} . We show that this assertion for a large class of sets does not hold for *all* irrational starting angles α .

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1. Introduction and statement of results

In this paper we will be concerned with bounded remainder sets for the two-dimensional billiard on the unit-square $I^2 = [0, 1)^2$.

DEFINITION 1. Let $\mathbf{x} = (x_1, x_2) \in I^2$ and let $\alpha \in \mathbb{R} \setminus \mathbb{Q}$. We say that the function $Y : [0, \infty) \rightarrow I^2$ defined by

$$Y(t) = \left(2 \cdot \left\| \frac{x_1 + t}{2} \right\|, 2 \cdot \left\| \frac{x_2 + \alpha t}{2} \right\| \right) \quad 0 \leq t < \infty, \quad (1)$$

where $\|z\| := \min_{a \in \mathbb{Z}} |z - a|$, is the two-dimensional billiard with starting slope α and starting point \mathbf{x} .

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It is easily checked that this definition indeed coincides with our image of a real billiard-path in the unit square.

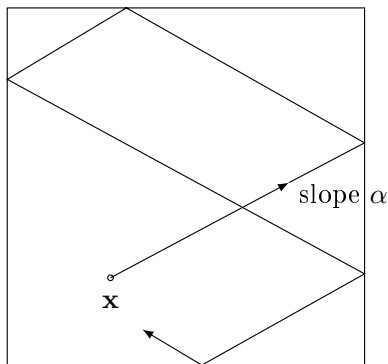


FIGURE 1.

DEFINITION 2. Let $S \subset I^2$ be an arbitrary measurable subset of the unit square with Lebesgue measure $\lambda(S)$. We say that S is a bounded remainder set for the two-dimensional billiard with starting slope α and starting point $\mathbf{x} = (x_1, x_2) \in I^2$ if the distribution error

$$\Delta_T^Y(S, \alpha, \mathbf{x}) = \int_0^T \chi_S(Y(t)) \, dt - T\lambda(S) \quad (2)$$

is uniformly bounded for all $T > 0$. Here, χ_S denotes the characteristic function for the set S .

Distribution properties for continuous motions in an s -dimensional unit cube were studied, for example, by *Drmota* in [3] (see also [4] or [7]) and quite recently by *Beck* [1]. *Beck* ([1], [2]), especially studied continuous irrational rotations and billiard paths. For the two-dimensional billiard path, for example, he showed the following surprising result:

THEOREM (Beck). *Let $S \subseteq I^2$ be an arbitrary Lebesgue measurable set in the unit square with positive measure. Then for every $\epsilon > 0$, almost all $\alpha > 0$ and every starting point $\mathbf{x} = (x_1, x_2) \in I^2$ we have*

$$\Delta_T^Y(S, \alpha, \mathbf{x}) = o\left((\log T)^{3+\epsilon}\right). \quad (3)$$

As pointed out by *Beck*, the poly-logarithmic error term is shockingly small compared to the linear term $T\lambda(S)$. Moreover, it holds for *all* measurable sets S . It is thus natural to ask if imposing certain regularity conditions on S could give an even lower bound on the error term.

We demonstrate in the following that the estimate of Beck indeed can be significantly improved for a large collection of sets S . We show:

THEOREM 1.

- a) *For almost all $\alpha > 0$ and every $\mathbf{x} \in I^2$, every polygon $S \subset I^2$ with no edge of slope α or $-\alpha$ is a bounded remainder set for the two-dimensional billiard with starting slope α and starting point \mathbf{x} .*
- b) *For almost all $\alpha > 0$ and every $\mathbf{x} = (x_1, x_2) \in I^2$, every convex set $S \subset I^2$ whose boundary ∂S is a twice continuously differentiable curve with positive curvature at every point is a bounded remainder set for the two-dimensional billiard with starting slope α and starting point \mathbf{x} .*

We will see in the proofs of these results that this Theorem easily follows from an analogous result shown in [5] for the continuous irrational rotation $X(t) := (\{x_1 + t\}, \{x_2 + \alpha t\})_{t \geq 0}$, and by the “unfolding-technique” suggested by Beck in [2]. It is obvious that the results given in Theorem 1 do not hold for a rational slope α . However, one could ask whether the results can be improved first by omitting the condition on the slopes of the edges of the polygon S in part a) of the Theorem and, second, whether both results maybe are valid even for *all* irrational slopes α . We will give an easy argument that indeed the condition on the slopes of the edges cannot be omitted in general. Moreover, we will prove - and this will be the main effort in this paper - that the results of Theorem 1a and 1b in general do not hold for *all* irrational α .

I.e., we will show:

THEOREM 2.

- a) *For every $\alpha > 0$ there is a polygon S with an edge of slope α or $-\alpha$ such that S is not a bounded remainder set for the billiard with starting-slope α and for any starting point \mathbf{x} .*
- b) *For every $\mathbf{m} \in [0, 1]^2$ there are uncountably many radii r , dense in an interval of positive length, such that there is a slope α and a starting point \mathbf{x} such that the disk with midpoint \mathbf{m} and radius r is not a set of bounded remainder with respect to the billiard with starting slope α and starting point \mathbf{x} .*

In Chapter 2 we prove Theorem 1 and Theorem 2a. In Chapter 3 we carry out the main work, namely the proof of Theorem 2 b.

2. Proofs of Theorem 1 and of Theorem 2a

The proofs of these two results can be traced back to the results given in [5] via the technique of unfolding.

As was pointed out in detail, for example, by Beck in [2] the technique of “unfolding” a billiard path (see Figure 2) shows that the problem of uniformity

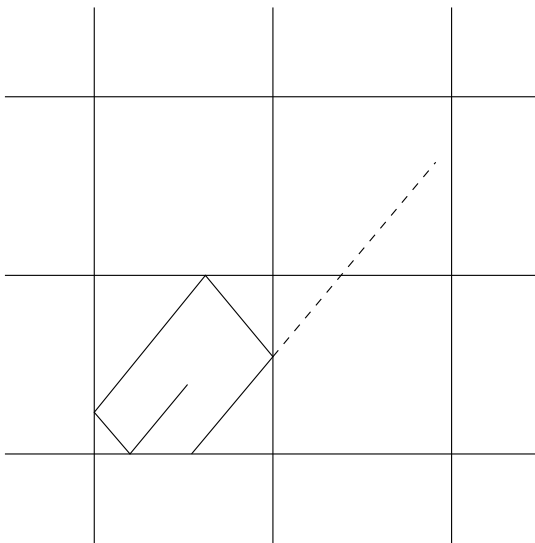


FIGURE 2.

of a billiard path in the unit square with respect to a given test set S is equivalent to the problem of uniformity of the corresponding continuous rotation in the 2×2 square, where each one of the four unit-sub-squares contains a reflected copy of the given test set (see S_1, S_2, S_3, S_4 in Figure 3) Of course, this again can be reduced to the problem of studying continuous irrational rotation in $[0, 1)^2$ with respect to a factor $1/2$ reduced versions of S_1, S_2, S_3, S_4 .

So in all the following, when studying the distribution error $\Delta_T^Y(S, \alpha, \mathbf{x})$ for the two-dimensional billiard this task can be traced back to the investigation of the distribution error $\Delta_T^X(\tilde{S}, \alpha, \mathbf{x})$ for the continuous irrational rotation where \tilde{S} consists of four mirrored and by a factor $1/2$ reduced copies of S lying symmetrical to $(1/2, 1/2)$.

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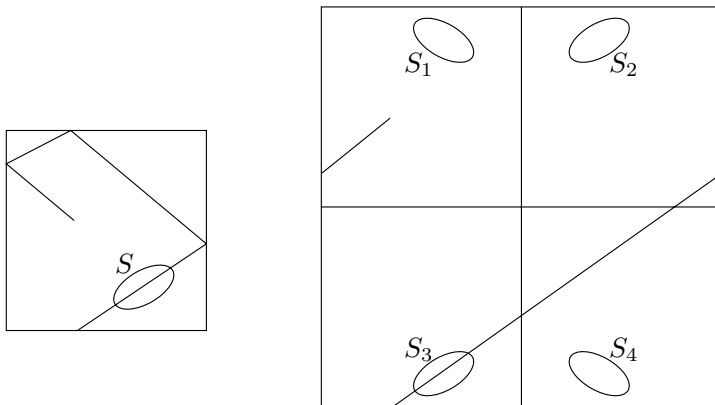


FIGURE 3.

Proof of Theorem 1. Theorem 1 follows immediately from the above considerations on the unfolding technique and from Theorem 1 and Theorem 2 in [5]. \square

Proof of Theorem 2a. Let $\alpha > 0$ be given. Consider first a triangle S (see Figure 4) with corners in $(a, 1)$, $(1, 1 - \alpha a)$, $(1, 1)$, where a is such that $0 < \alpha a < 1$ and such that $a \neq \frac{1}{\alpha}\{k\alpha\}$ for all $k \in \mathbb{N}$.

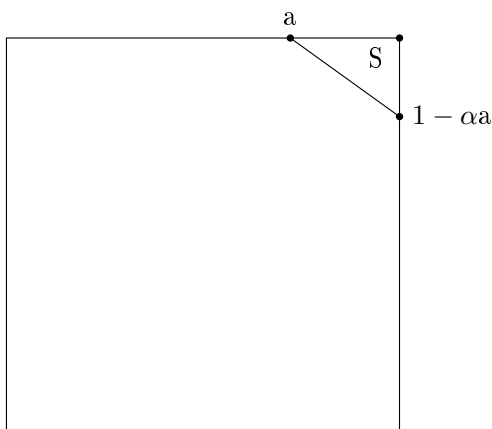


FIGURE 4.

So one side of S has slope $-\alpha$. Unfolding leads to the investigation of the continuous irrational rotation with slope α with respect to the parallelogram \tilde{S} (see Figure 5) with corners in

$$\left(\frac{1}{2}, \frac{a}{2}\right), \left(\frac{1}{2}, \frac{1+\alpha a}{2}\right), \left(\frac{1}{2} + \frac{a}{2}, \frac{1}{2}\right), \left(\frac{1}{2}, \frac{1-\alpha a}{2}\right).$$

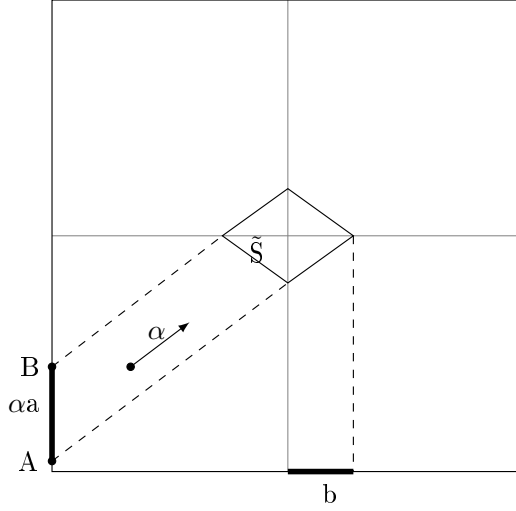


FIGURE 5.

Note that two sides of \tilde{S} have slope α , the other two have slope $-\alpha$. Its vertical diagonal $[A, B]$ has a length of $a\alpha \neq \{k\alpha\}$ for all $k \in \mathbb{N}$. We show that for no starting point \mathbf{x} the set \tilde{S} is of bounded remainder for the irrational continuous rotation with slope α . Hence the set S is not of bounded remainder for the billiard with starting slope α (and any starting point \mathbf{x}).

Indeed, it is easy to see that for this set \tilde{S} we have

$$\left| \int_0^T \chi_{\tilde{S}}(\{t\}, \{\alpha t\}) dt - b \cdot \sum_{n=1}^{[T]} \chi_{[A, B]}(\{n\alpha\}) \right| \leq 1.$$

It was shown by Kesten in [6] that

$$\left| \sum_{n=1}^{[T]} \chi_{[A, B]}(\{n\alpha\}) - a\alpha \cdot [T] \right|$$

is unbounded since $B - A = a\alpha \neq \{k\alpha\}$ for all $k \in \mathbb{N}$.

Hence (note that $\lambda(\tilde{S}) = a\alpha \cdot b$)

$$\left| \int_0^T \chi_{\tilde{S}}(\{t\}, \{\alpha t\}) dt - T \cdot \lambda(\tilde{S}) \right|$$

is unbounded. □

3. Proof of Theorem 2 b

The proof of Theorem 2b will need the most work. We start with some auxiliary results. Especially we will have to deal with functions of the form

$$g_m(x) := \frac{1}{2m} \sum_{k=0}^{2m-1} \sqrt{1 - \left(1 - \frac{k}{m} - x\right)^2} \quad (4)$$

for $x \in [0, \frac{1}{m}]$, where m is a given positive integer. The function g_m is illustrated in Figure 6.

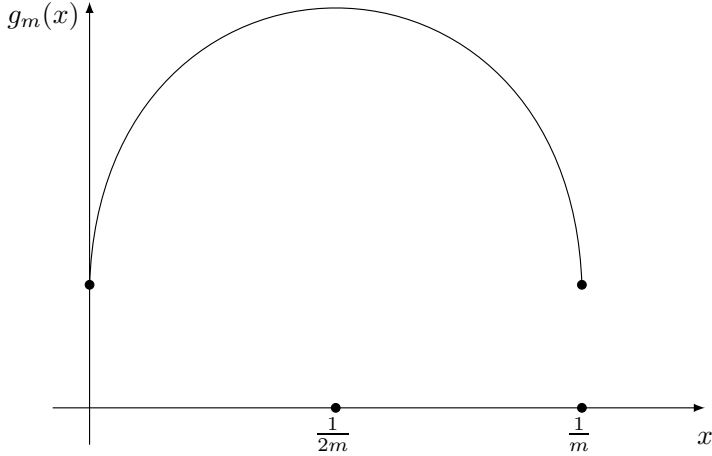


FIGURE 6.

Let now m be fixed, and $h_m(x) := g_m(x) - g_m(0)$. It is easy to see that

$$h_m(0) = h_m\left(\frac{1}{m}\right) = 0, \quad h_m$$

is arbitrarily often differentiable on $(0, \frac{1}{m})$, continuous on $[0, \frac{1}{m}]$, symmetric around $\frac{1}{2m}$ and strictly convex on $[0, \frac{1}{m}]$.

Further we have

LEMMA 1.

a) *There exist c', c'' with $0 < c' < c''$ such that for all m large enough we have*

$$c' \cdot \frac{1}{m^{3/2}} < h_m\left(\frac{1}{2m}\right) < c'' \cdot \frac{1}{m^{3/2}}. \quad (5)$$

b) *There exists $c''' > 0$ such that*

$$h_m(x) \geq c''' \cdot \frac{1}{m} \sqrt{x} \quad (6)$$

for all $x \in [0, \frac{1}{2m}]$.

Proof. This is shown by some tedious but elementary analysis. We do not give all details but just give two hints:

• To prepare part a) note that

$$\begin{aligned} h_m(x) &= g_m(x) - g_m(0) \\ &= \frac{1}{2m} \sum_{k=0}^{2m-1} \left(\sqrt{1 - \left(1 - \frac{k}{m} - x\right)^2} - \sqrt{1 - \left(1 - \frac{k}{m}\right)^2} \right) \\ &= \frac{1}{2m} \sum_{k=0}^m \left(\sqrt{1 - \left(1 - \frac{k}{m} - x\right)^2} - \sqrt{1 - \left(1 - \frac{k}{m}\right)^2} \right) \\ &\quad + \sqrt{1 - \left(1 - \frac{2m-1-k}{m} - x\right)^2} - \sqrt{1 - \left(1 - \frac{2m-1-k}{m}\right)^2} \\ &=: \frac{1}{2m} \sum_{k=0}^m w_m(k, x) \end{aligned}$$

and note that simple calculation shows that for $k \geq 0$ there are absolute constants $c'_1, c'_2 > 0$ such that

$$c'_1 \cdot \frac{1}{m^{1/2} \max(k, 1)^{3/2}} \leq w_m(k, \frac{1}{2m}) \leq c'_2 \cdot \frac{1}{m^{1/2} \max(k, 1)^{3/2}},$$

always.

• To show part b, note that for x small, only the first summand of h_m , i.e., the summand for $k=0$,

$$\frac{1}{m} \sqrt{1 - (1 - x)^2} \sim \frac{1}{m} \sqrt{x}$$

is of relevance. □

LEMMA 2.

a) *There exists $c_1 > 0$ such that*

$$\left| h'_m(x) \right| \leq c_1 \cdot \frac{1}{\sqrt{m}} \quad (7)$$

for all $x \in [\frac{1}{10m}, \frac{9}{10m}]$ and all m large enough.

Especially, it holds that

$$h'_m(x) \geq -c_1 \cdot \frac{1}{\sqrt{m}} \quad (8)$$

for all $x \in [0, \frac{9}{10m}]$.

b) *There exists $c_2 > 0$ such that for all m large enough we have*

$$h'_m(x) \geq 5c_1 \frac{1}{\sqrt{m}} \quad (9)$$

for all $x \in (0, c_2 \frac{1}{m})$.

(Here c_1 is the constant from part a).)

Proof. This follows immediately from Lemma 1 and the convexity of h_m . \square

Let m large enough be fixed. Moreover, in the following let a, b, c be given reals with

$$0 \leq a \leq b \leq c < \frac{1}{m},$$

and

$$\begin{aligned} G_m(x) &:= g_m\left(x\right) + g_m\left((x+a) \bmod \frac{1}{m}\right) \\ &\quad + g_m\left((x+b) \bmod \frac{1}{m}\right) + g_m\left((x+c) \bmod \frac{1}{m}\right). \end{aligned}$$

Then we have:

LEMMA 3. *There are $c_3, c_4 > 0$ such that for all m large enough and all a, b, c as above there is an $x_0 \in \{0, a, b, c\}$ such that G_m is strictly increasing on $[x_0, x_0 + c_4 \cdot \frac{1}{m}]$ and*

$$G_m\left(x_0 + c_4 \cdot \frac{1}{3m}\right) - G_m(x_0) > c_3 \cdot \frac{1}{m^{3/2}}, \quad (10)$$

$$G_m\left(x_0 + c_4 \cdot \frac{2}{3m}\right) - G_m\left(x_0 + c_2 \cdot \frac{1}{3m}\right) > c_3 \cdot \frac{1}{m^{3/2}}, \quad (11)$$

$$G_m\left(x_0 + c_4 \cdot \frac{1}{m}\right) - G_m\left(x_0 + c_2 \cdot \frac{2}{3m}\right) > c_3 \cdot \frac{1}{m^{3/2}}. \quad (12)$$

Proof. At least one of the following relations holds:

$$c < \frac{4}{5m} \quad \text{or} \quad b < c - \frac{1}{5m}, \quad \text{or} \quad a < b - \frac{1}{5m}, \quad \text{or} \quad a > \frac{1}{5m}.$$

Assume for example that $c < \frac{4}{5m}$ holds (the other cases are treated quite analogously). Then set $x_0 = 0$. Let $c_4 := \min(c_2, \frac{1}{10})$ where c_2 is like in Lemma 2 b). Then for any $x \in [0, c_4 \frac{1}{m}]$ it holds that

$$(a+x) \bmod \frac{1}{m}, \quad \text{and} \quad (b+x) \bmod \frac{1}{m}, \quad \text{and} \quad (c+x) \bmod \frac{1}{m} \quad \text{are all in} \quad \left[0, \frac{9}{10m}\right).$$

Hence by Lemma 2 a) we have that g'_m at these places is at least $-c_1 \cdot \frac{1}{\sqrt{m}}$. By Lemma 2 b) for $x \in [0, c_4 \frac{1}{m}]$ we have $g'_m(x) \geq 5c_1 \cdot \frac{1}{\sqrt{m}}$ and hence $G'_m(x) \geq 2c_1 \frac{1}{\sqrt{m}}$ for all those x .

From this the assertions of Lemma 3 immediately follow. \square

LEMMA 4. *For all m large enough there is a sub-interval Λ_m of $[0, \frac{1}{m}]$ of length at least $\frac{c_4}{3} \cdot \frac{1}{m}$ such that either*

$$G_m(x) > 2 \int_0^2 \sqrt{1 - (1-y)^2} dy + \frac{c_3}{2m^{3/2}} = \pi + \frac{c_3}{2m^{3/2}} \quad (13)$$

or

$$G_m(x) < 2 \int_0^2 \sqrt{1 - (1-y)^2} dy - \frac{c_3}{2m^{3/2}} = \pi - \frac{c_3}{2m^{3/2}} \quad (14)$$

holds for all $x \in \Lambda_m$.

Proof. This follow immediately from Lemma 3. \square

Proof of Theorem 2 b. For the proof we proceed in analogy to the proof of Theorem 1.7 b in [5], where the corresponding result was shown for the continuous irrational rotation, and in the following we sometimes refer to this proof.

Fix an irrational $\alpha \in (\frac{1}{8}, \frac{1}{4})$ with continued fraction expansion $\alpha = [0; a_1, a_2, \dots]$ and convergents $\frac{p_n}{q_n}$ satisfying $a_{l+1} > q_l^{100}$ and p_l even, for infinitely many l . There exist uncountably many such α s. Let S be a disk with diameter $d := 2\alpha/\sqrt{1+\alpha^2}$. (Note that the set of α with the above properties is dense in $(\frac{1}{8}, \frac{1}{4})$, hence the set of diameters d is dense in $(\frac{2}{\sqrt{65}}, \frac{2}{\sqrt{17}})$.)

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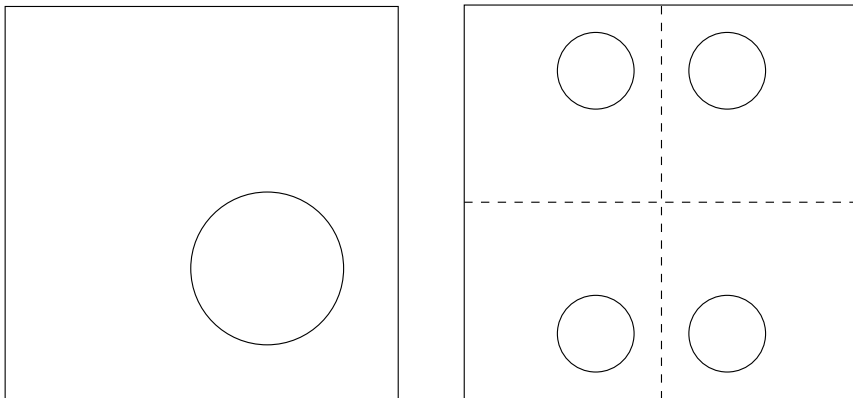


FIGURE 7.

Studying the billiard path with respect to S means to study the continuous rotation with respect to four copies of S with diameter $\alpha/\sqrt{1+\alpha^2}$ each (see Figure 7)

For such α and one copy of such disks it was shown in Theorem 1.7 b in [5] that the continuous rotation is not of bounded remainder for all starting points \mathbf{x} . In the proof of this Theorem the result was shown by studying the function g_m as defined in this current paper at the beginning of Section 3 (in [5] our g_m is denoted by G_m), and it was shown that the validity of the result of Theorem 1.7 b in [5] is due to the fact that for every m there exists a subinterval $\Lambda_m \subseteq [0, \frac{1}{2m}]$ of length at least $\frac{1}{6m}$ such that either

$$g_m(x) > \frac{1}{2} \int_0^2 \sqrt{1 - (1-y)^2} \, dy + \frac{\tilde{c}}{m^{3/2}} = \frac{\pi}{4} + \frac{\tilde{c}}{m^{3/2}} \quad (15)$$

or

$$g_m(x) < \frac{1}{2} \int_0^2 \sqrt{1 - (1-y)^2} \, dy - \frac{\tilde{c}}{m^{3/2}} = \frac{\pi}{4} - \frac{\tilde{c}}{m^{3/2}} \quad (16)$$

holds for an absolute constant $\tilde{c} > 0$ and all $x \in \Lambda_m$.

By following the proof of Theorem 1.7 b in [5] it becomes obvious that studying now four copies of disks instead of one copy means to study

$$g_m(x) + g_m\left((x+a) \bmod \frac{1}{m}\right) + g_m\left((x+b) \bmod \frac{1}{m}\right) + g_m\left((x+c) \bmod \frac{1}{m}\right)$$

for some a, b, c .

This means in particular to analyse the corresponding function G_m as it has been done in Lemma 3 and Lemma 4 of the current paper. In Lemma 4 it was shown that for G_m an analogous property (independent of the choices for a, b , and c) holds as stated above for g_m .

Again by following the proof of Theorem 1.7 b in [5] it is obvious that from this property for G_m (Lemma 4) the result of our Theorem 2 b follows. □

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