Jordan Matrix Decomposition

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Summary. In this paper I present the Jordan Matrix Decomposition Theorem which states that an arbitrary square matrix M over an algebraically closed field can be decomposed into the form

 $M = SJS^{-1}$

where S is an invertible matrix and J is a matrix in a Jordan canonical form, i.e. a special type of block diagonal matrix in which each block consists of Jordan blocks (see [13]).

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The terminology and notation used here are introduced in the following articles: [11], [2], [3], [12], [34], [7], [10], [8], [4], [28], [33], [30], [18], [6], [14], [15], [36], [23], [37], [35], [9], [29], [32], [31], [5], [19], [24], [22], [17], [1], [21], [20], [16], [25], [27], and [26].

1. JORDAN BLOCKS

We follow the rules: i, j, m, n, k denote natural numbers, K denotes a field, and a, λ denote elements of K.

Let us consider K, λ , n. The Jordan block of λ and n yields a matrix over K and is defined by the conditions (Def. 1).

(Def. 1)(i) len (the Jordan block of λ and n) = n,

(ii) width (the Jordan block of λ and n) = n, and

(iii) for all i, j such that $\langle i, j \rangle \in$ the indices of the Jordan block of λ and n holds if i = j, then (the Jordan block of λ and n)_{$i,j} = <math>\lambda$ and if i + 1 = j, then (the Jordan block of λ and n)_{$i,j} = <math>\mathbf{1}_K$ and if $i \neq j$ and $i + 1 \neq j$, then (the Jordan block of λ and n)_{$i,j} = <math>\mathbf{0}_K$.</sub></sub></sub>

C 2008 University of Białystok ISSN 1426-2630(p), 1898-9934(e) Let us consider K, λ , n. Then the Jordan block of λ and n is an upper triangular matrix over K of dimension n.

The following propositions are true:

- (1) The diagonal of the Jordan block of λ and $n = n \mapsto \lambda$.
- (2) Det (the Jordan block of λ and n) = power_K(λ , n).
- (3) The Jordan block of λ and n is invertible iff n = 0 or $\lambda \neq 0_K$.
- (4) If $i \in \text{Seg } n$ and $i \neq n$, then Line(the Jordan block of λ and n, i) = $\lambda \cdot \text{Line}(I_K^{n \times n}, i) + \text{Line}(I_K^{n \times n}, i+1).$
- (5) Line(the Jordan block of λ and n, n) = $\lambda \cdot \text{Line}(I_K^{n \times n}, n)$.
- (6) Let F be an element of (the carrier of K)ⁿ such that $i \in \text{Seg } n$. Then
- (i) if $i \neq n$, then Line(the Jordan block of λ and n, i) $\cdot F = \lambda \cdot F_i + F_{i+1}$, and
- (ii) if i = n, then Line(the Jordan block of λ and n, i) $\cdot F = \lambda \cdot F_i$.
- (7) Let F be an element of (the carrier of K)ⁿ such that $i \in \text{Seg } n$. Then
- (i) if i = 1, then (the Jordan block of λ and $n)_{\Box,i} \cdot F = \lambda \cdot F_i$, and
- (ii) if $i \neq 1$, then (the Jordan block of λ and $n)_{\Box,i} \cdot F = \lambda \cdot F_i + F_{i-1}$.
- (8) Suppose $\lambda \neq 0_K$. Then there exists a square matrix M over K of dimension n such that
- (i) (the Jordan block of λ and $n)^{\sim} = M$, and
- (ii) for all i, j such that $\langle i, j \rangle \in$ the indices of M holds if i > j, then $M_{i,j} = 0_K$ and if $i \le j$, then $M_{i,j} = -\text{power}_K(-\lambda^{-1}, (j i) + 1)$.
- (9) (The Jordan block of λ and n) + $a \cdot I_K^{n \times n}$ = the Jordan block of $\lambda + a$ and n.

2. Finite Sequences of Jordan Blocks

Let us consider K and let G be a finite sequence of elements of $((\text{the carrier of } K)^*)^*$. We say that G is Jordan-block-yielding if and only if:

(Def. 2) For every *i* such that $i \in \text{dom } G$ there exist λ , *n* such that G(i) = the Jordan block of λ and *n*.

Let us consider K. Observe that there exists a finite sequence of elements of $((\text{the carrier of } K)^*)^*$ which is Jordan-block-yielding.

Let us consider K. One can verify that every finite sequence of elements of $((\text{the carrier of } K)^*)^*$ which is Jordan-block-yielding is also square-matrix-yielding.

Let us consider K. A finite sequence of Jordan blocks of K is a Jordan-blockyielding finite sequence of elements of $((\text{the carrier of } K)^*)^*$.

Let us consider K, λ . A finite sequence of Jordan blocks of K is said to be a finite sequence of Jordan blocks of λ and K if: (Def. 3) For every *i* such that $i \in \text{dom it there exists } n$ such that $\text{it}(i) = \text{the Jordan block of } \lambda$ and n.

Next we state two propositions:

- (10) \emptyset is a finite sequence of Jordan blocks of λ and K.
- (11) (the Jordan block of λ and n) is a finite sequence of Jordan blocks of λ and K.

Let us consider K, λ . Observe that there exists a finite sequence of Jordan blocks of λ and K which is non-empty.

Let us consider K. Note that there exists a finite sequence of Jordan blocks of K which is non-empty.

Next we state the proposition

(12) Let J be a finite sequence of Jordan blocks of λ and K. Then $J \oplus \text{len } J \mapsto a \bullet I_K^{\text{Len } J \times \text{Len } J}$ is a finite sequence of Jordan blocks of $\lambda + a$ and K.

Let us consider K and let J_1 , J_2 be fininte sequences of Jordan blocks of K. Then $J_1 \cap J_2$ is a finite sequence of Jordan blocks of K.

Let us consider K, let J be a finite sequence of Jordan blocks of K, and let us consider n. Then $J \upharpoonright n$ is a finite sequence of Jordan blocks of K. Then $J_{\mid n}$ is a finite sequence of Jordan blocks of K.

Let us consider K, λ and let J_1 , J_2 be finite sequences of Jordan blocks of λ and K. Then $J_1 \cap J_2$ is a finite sequence of Jordan blocks of λ and K.

Let us consider K, λ , let J be a finite sequence of Jordan blocks of λ and K, and let us consider n. Then $J \upharpoonright n$ is a finite sequence of Jordan blocks of λ and K. Then $J_{\lfloor n}$ is a finite sequence of Jordan blocks of λ and K.

3. NILPOTENT TRANSFORMATIONS

Let K be a double loop structure, let V be a non empty vector space structure over K, and let f be a function from V into V. We say that f is nilpotent if and only if:

- (Def. 4) There exists n such that for every vector v of V holds $f^n(v) = 0_V$. We now state the proposition
 - (13) Let K be a double loop structure, V be a non empty vector space structure over K, and f be a function from V into V. Then f is nilpotent if and only if there exists n such that $f^n = \text{ZeroMap}(V, V)$.

Let K be a double loop structure and let V be a non empty vector space structure over K. Observe that there exists a function from V into V which is nilpotent.

Let R be a ring and let V be a left module over R. Observe that there exists a function from V into V which is nilpotent and linear.

Next we state the proposition

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(14) Let V be a vector space over K and f be a linear transformation from V to V. Then $f \upharpoonright \ker f^n$ is a nilpotent linear transformation from ker f^n to ker f^n .

Let K be a double loop structure, let V be a non empty vector space structure over K, and let f be a nilpotent function from V into V. The degree of nilpotence of f yielding a natural number is defined by the conditions (Def. 5).

- (Def. 5)(i) $f^{\text{the degree of nilpotence of } f} = \text{ZeroMap}(V, V)$, and
 - (ii) for every k such that $f^k = \text{ZeroMap}(V, V)$ holds the degree of nilpotence of $f \leq k$.

Let K be a double loop structure, let V be a non empty vector space structure over K, and let f be a nilpotent function from V into V. We introduce deg f as a synonym of the degree of nilpotence of f.

One can prove the following propositions:

- (15) Let K be a double loop structure, V be a non empty vector space structure over K, and f be a nilpotent function from V into V. Then deg f = 0 if and only if $\Omega_V = \{0_V\}$.
- (16) Let K be a double loop structure, V be a non empty vector space structure over K, and f be a nilpotent function from V into V. Then there exists a vector v of V such that for every i such that $i < \deg f$ holds $f^i(v) \neq 0_V$.
- (17) Let K be a field, V be a vector space over K, W be a subspace of V, and f be a nilpotent function from V into V. Suppose $f \upharpoonright W$ is a function from W into W. Then $f \upharpoonright W$ is a nilpotent function from W into W.
- (18) Let K be a field, V be a vector space over K, W be a subspace of V, f be a nilpotent linear transformation from V to V, and f_1 be a nilpotent function from $\operatorname{im}(f^n)$ into $\operatorname{im}(f^n)$. If $f_1 = f \upharpoonright \operatorname{im}(f^n)$ and $n \leq \deg f$, then $\deg f_1 + n = \deg f$.

For simplicity, we adopt the following convention: V_1 , V_2 denote finite dimensional vector spaces over K, W_1 , W_2 denote subspaces of V_1 , U_1 , U_2 denote subspaces of V_2 , b_1 denotes an ordered basis of V_1 , B_1 denotes a finite sequence of elements of V_1 , b_2 denotes an ordered basis of V_2 , B_2 denotes a finite sequence of elements of V_2 , b_3 denotes an ordered basis of W_1 , b_4 denotes an ordered basis of W_2 , B_3 denotes a finite sequence of elements of U_1 , and B_4 denotes a finite sequence of elements of U_2 .

Next we state a number of propositions:

(19) Let M be a matrix over K of dimension len $b_1 \times \text{len } B_2$, M_1 be a matrix over K of dimension len $b_3 \times \text{len } B_3$, and M_2 be a matrix over K of dimension len $b_4 \times \text{len } B_4$ such that $b_1 = b_3 \cap b_4$ and $B_2 = B_3 \cap B_4$ and $M = \text{the } 0_K$ -block diagonal of $\langle M_1, M_2 \rangle$ and width $M_1 = \text{len } B_3$ and width $M_2 = \text{len } B_4$. Then

- (i) if $i \in \text{dom } b_3$, then $(\text{Mx2Tran}(M, b_1, B_2))((b_1)_i) = (\text{Mx2Tran}(M_1, b_3, B_3))((b_3)_i)$, and
- (ii) if $i \in \text{dom} b_4$, then $(\text{Mx2Tran}(M, b_1, B_2))((b_1)_{i+\text{len} b_3}) = (\text{Mx2Tran}(M_2, b_4, B_4))((b_4)_i).$
- (20) Let M be a matrix over K of dimension len $b_1 \times \text{len } B_2$ and F be a finite sequence of matrices over K. Suppose $M = \text{the } 0_K$ -block diagonal of F. Let given i, m. Suppose $i \in \text{dom } b_1$ and $m = \min(\text{Len } F, i)$. Then $(\text{Mx2Tran}(M, b_1, B_2))((b_1)_i) = \sum \text{lmlt}(\text{Line}(F(m), i \sum \text{Len}(F \upharpoonright (m '1))), (B_2 \upharpoonright \sum \text{Width}(F \upharpoonright m))_{i \ge \text{Width}(F \upharpoonright (m '1))})$ and $\text{len}((B_2 \upharpoonright \sum \text{Width}(F \upharpoonright m))_{i \ge \text{Width}(F \upharpoonright (m '1))}) = \text{width } F(m).$
- (21) If len $B_1 \in \text{dom} B_1$, then $\sum \text{lmlt}(\text{Line}(\text{the Jordan block of } \lambda \text{ and } \text{len } B_1, \text{len } B_1), B_1) = \lambda \cdot (B_1)_{\text{len } B_1}.$
- (22) If $i \in \text{dom } B_1$ and $i \neq \text{len } B_1$, then $\sum \text{lmlt}(\text{Line}(\text{the Jordan block of } \lambda \text{ and len } B_1, i), B_1) = \lambda \cdot (B_1)_i + (B_1)_{i+1}$.
- (23) Let M be a matrix over K of dimension len $b_1 \times \text{len } B_2$. Suppose M = the Jordan block of λ and n. Let given i such that $i \in \text{dom } b_1$. Then
 - (i) if $i = \operatorname{len} b_1$, then $(\operatorname{Mx2Tran}(M, b_1, B_2))((b_1)_i) = \lambda \cdot (B_2)_i$, and
- (ii) if $i \neq \text{len } b_1$, then $(\text{Mx2Tran}(M, b_1, B_2))((b_1)_i) = \lambda \cdot (B_2)_i + (B_2)_{i+1}$.
- (24) Let J be a finite sequence of Jordan blocks of λ and K and M be a matrix over K of dimension len $b_1 \times \text{len } B_2$. Suppose $M = \text{the } 0_K$ -block diagonal of J. Let given i, m such that $i \in \text{dom } b_1$ and $m = \min(\text{Len } J, i)$. Then
 - (i) if $i = \sum \operatorname{Len}(J \upharpoonright m)$, then $(\operatorname{Mx2Tran}(M, b_1, B_2))((b_1)_i) = \lambda \cdot (B_2)_i$, and
- (ii) if $i \neq \sum \operatorname{Len}(J \upharpoonright m)$, then $(\operatorname{Mx2Tran}(M, b_1, B_2))((b_1)_i) = \lambda \cdot (B_2)_i + (B_2)_{i+1}$.
- (25) Let J be a finite sequence of Jordan blocks of 0_K and K and M be a matrix over K of dimension len $b_1 \times \text{len } b_1$. Suppose M = the 0_K -block diagonal of J. Let given m. If for every i such that $i \in \text{dom } J$ holds len $J(i) \leq m$, then $(\text{Mx2Tran}(M, b_1, b_1))^m = \text{ZeroMap}(V_1, V_1)$.
- (26) Let J be a finite sequence of Jordan blocks of λ and K and M be a matrix over K of dimension len $b_1 \times \text{len } b_1$. Suppose M = the 0_K -block diagonal of J. Then Mx2Tran (M, b_1, b_1) is nilpotent if and only if len $b_1 = 0$ or $\lambda = 0_K$.
- (27) Let J be a finite sequence of Jordan blocks of 0_K and K and M be a matrix over K of dimension len $b_1 \times \text{len } b_1$. Suppose M = the 0_K -block diagonal of J and len $b_1 > 0$. Let F be a nilpotent function from V_1 into V_1 . Suppose $F = \text{Mx2Tran}(M, b_1, b_1)$. Then there exists i such that $i \in \text{dom } J$ and len J(i) = deg F and for every i such that $i \in \text{dom } J$ holds len $J(i) \leq \text{deg } F$.
- (28) Let given V_1 , V_2 , b_1 , b_2 , λ . Suppose len $b_1 = \text{len } b_2$. Let F be a linear

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transformation from V_1 to V_2 . Suppose that for every i such that $i \in \text{dom } b_1$ holds $F((b_1)_i) = \lambda \cdot (b_2)_i$ or $i+1 \in \text{dom } b_1$ and $F((b_1)_i) = \lambda \cdot (b_2)_i + (b_2)_{i+1}$. Then there exists a non-empty finite sequence J of Jordan blocks of λ and K such that $\text{AutMt}(F, b_1, b_2) = \text{the } 0_K$ -block diagonal of J.

- (29) Let V_1 be a finite dimensional vector space over K and F be a nilpotent linear transformation from V_1 to V_1 . Then there exists a non-empty finite sequence J of Jordan blocks of 0_K and K and there exists an ordered basis b_1 of V_1 such that AutMt (F, b_1, b_1) = the 0_K -block diagonal of J.
- (30) Let V be a vector space over K, F be a linear transformation from V to V, V_1 be a finite dimensional subspace of V, and F_1 be a linear transformation from V_1 to V_1 . Suppose $V_1 = \ker (F + (-\lambda) \cdot \mathrm{id}_V)^n$ and $F \upharpoonright V_1 = F_1$. Then there exists a non-empty finite sequence J of Jordan blocks of λ and K and there exists an ordered basis b_1 of V_1 such that $\operatorname{AutMt}(F_1, b_1, b_1) = \operatorname{the} 0_K$ -block diagonal of J.

4. The Main Theorem

The following two propositions are true:

- (31) Let K be an algebraic-closed field, V be a non trivial finite dimensional vector space over K, and F be a linear transformation from V to V. Then there exists a non-empty finite sequence J of Jordan blocks of K and there exists an ordered basis b_1 of V such that
 - (i) $\operatorname{AutMt}(F, b_1, b_1) = \operatorname{the} 0_K$ -block diagonal of J, and
- (ii) for every scalar λ of K holds λ is an eigenvalue of F iff there exists i such that $i \in \text{dom } J$ and $J(i) = \text{the Jordan block of } \lambda$ and len J(i).
- (32) Let K be an algebraic-closed field and M be a square matrix over K of dimension n. Then there exists a non-empty finite sequence J of Jordan blocks of K and there exists a square matrix P over K of dimension n such that $\sum \text{Len } J = n$ and P is invertible and $M = P \cdot \text{the } 0_K\text{-block}$ diagonal of $J \cdot P^{\sim}$.

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