STRESS INTENSITY FACTOR CALCULATIONS FOR THE COMPRESSOR BLADE WITH HALF-ELLIPTICAL SURFACE CRACK USING RAJU-NEWMAN SOLUTION

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Abstract

This paper presents results of the stress intensity factor calculations for the compressor blade including a half-elliptical crack, subjected to vibration. In this analysis, the Raju-Newman empirical solution for stress intensity factor calculations in the rectangular plate with a halfelliptical flaw was used. The bending stress used in the Raju-Newman solution was computed for the real blade using the finite element method. The K-factor values were calculated only at one point of the crack front, where the crack tip contacts the free surface, because the crack length during experimental investigations was measured just in this direction. In order to determine the stress intensity factors for different crack sizes, ten diverse flaws in the blade were defined. Results of the experimental fatigue tests performed for the blade without preliminary defects showed that the cracks developed from the convex blade surface. On the blade fracture, the beach marks typical of the fatigue damage were visible. The dimensions of cracks in the rectangular plate were defined based on the beach marks shape. In the next part of the work, the stress intensity factor values were used as an input data into the Paris-Erdogan equation. As a result of this calculation, the crack growth rate for the compressor blade vibrating at constant amplitude was estimated. The results obtained were finally compared with the results of the experimental crack growth analysis performed for 1st stage compressor blades of the helicopter turbo-engine.

1. INTRODUCTION

The stress intensity factor is one of the main parameters defined in the fracture mechanics. The stress intensity factor (designated as: SIF, K or K-factor) has a big influence on the crack growth rate. The K-factor calculation is not easy, especially for geometrically complex structures. In engineering applications, K-factor is often computed numerically using a finite element method (FEM) or a boundary element method (BEM). SIF calculation using FEM is not easy as special degenerated finite elements must be used for the definition of the model zone near the crack tip. The process of element degeneration is usually non-automatic and also very time-consuming.

In 1981 Raju and Newman Jr. published the paper [1] in which the empirical solution for stress intensity factor calculations concerning simple 3D structures was given. In this paper, the solution for the crack intensity factors calculations, for the half-elliptical crack embedded in the compressor blade, was described.

The crack growth analysis of turbine or compressor components has been the focus of several investigations. The crack propagation problem of the high rotational parts used in aviation and also in the power engineering was described by: Barlow et al. [2], Poursaeidi et al. [3], Nikhamkin et

al. [4] and Troshchenko et al. [5]. The stress intensity factor calculation for the turbine disc with the corner crack using FEM was also described in [6].

The main intention of this work is the stress intensity factor estimation for the compressor blade with a half-elliptical crack based on the Raju-Newman solution. The attention of this paper is also devoted to the crack growth rate determination for the 1st stage compressor blade subjected to vibration at constant amplitude.

2. COMPRESSOR BLADE DAMAGED IN FATIGUE TEST

During the stress intensity factor empirical calculations, certain information from the experimental investigations will be used. Thus, the experimental investigations and the object of these investigations should be firstly described.

The 1st stage blade of the PZL-10W turbo-engine (Figs. 1a and 1b) was made from EI-961 austenitic steel (0.11C; 11Cr; 1.5Ni, 1.6 W; 0.18V; 0.35Mo; 0.025S; 0.03P) with the following properties (in 20°C) after heat treatment: ultimate tensile strength 900-1090 MPa, yield stress 800-900 MPa, Young modulus 200 GPa, Poisson ratio 0.3.

The blade during vibration is periodically bent to the left and right side (Fig.1c). Since the cross-section of the blade is non-symmetric, the stress levels under the left and right deflections of blade are different. In the description of the stress analysis results, the information about blade deflection will be placed.



Fig. 1. First stage compressor blade after fatigue test (a), the most frequent crack location in the blade without preliminary defects (b) and the 1st mode of transverse vibrations shape (c)

The fatigue tests performed for the compressor blades were made under the research project No. N N 504 346736, supported by the Polish Ministry of Science and Higher Education. In this project, both non-defected blades and also the ones with preliminary mechanical defects were considered. All experimental investigations were performed at Research and Development Laboratory for Aerospace Materials at the Rzeszów University of Technology. The results of these investigations are shown in Figs. 1a, 2 and 5a. The results of the experimental fatigue tests performed for the blade without preliminary defects are described in work [7].

In Fig. 2 the fatigue fracture of the blade in the preliminary phase of fatigue was shown. Just after the preliminary crack formation, the blade was statically tensioned and ruptured with the use of the testing machine. As seen in Fig. 2, in the blade without mechanical defects or corrosion pits, the crack usually propagates from the convex surface.



Fig. 2. A half-elliptical crack emanating from the convex blade surface, in the preliminary phase of fracture

3. RAJU-NEWMAN EMPIRICAL SOLUTION FOR STRESS INTENSITY FACTOR CALCULATIONS FOR SEMI-ELLIPTICAL FLAW IN FLAT PLATE

In 1981 Raju and Newman Jr. published the paper [1] in which the empirical solutions for stress intensity factor calculations for simple 3D structures were given. According to Raju-Newman, the stress intensity factor (K_I) for the semi-elliptical crack embedded in the flat plate subjected to pure bending (Fig. 3) can be determined by the following equation [1]:

$$K_{I} = H \times \sigma_{b} \times \sqrt{\frac{\pi \times a}{Q}} \times F\left(\frac{a}{t}; \frac{a}{c}; \frac{c}{W}; \varphi\right)$$
(1)

where:

 σ_b – bending stress, a – crack depth (Fig. 3). The different dimensions used in equation (1) are described in Figs. 3 and 4.

The F function is described by:

$$F = \left[M_1 + M_2 \left(\frac{a}{t}\right)^2 + M_3 \left(\frac{a}{t}\right)^4 \right] f_{\phi} \times f_w \times g$$
⁽²⁾

where:

$$M_1 = 1,13 - 0,09 \left(\frac{a}{c}\right)$$
(3)

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Fig. 3. Semi-elliptical crack embedded in the flat plate subjected to pure bending [1]



Fig. 4. Location of the point A on the crack front according to Raju-Newman method. Crack and cross-section dimensions [1]

$$M_2 = -0.54 + \frac{0.89}{0.2 + \frac{a}{c}}$$
(4)

$$M_{3} = 0.5 - \frac{1}{0.65 + \frac{a}{c}} + 14 \left(1 - \frac{a}{c}\right)^{24}$$
(5)

The Q function from equation (1) is given by:

$$Q = 1 + 1,464 \left(\frac{a}{c}\right)^{1,65}$$
(6)

The f_{ϕ} , f_w , and g functions from equation (2) can be expressed as follows:

$$f_{\varphi} = \left[\left(\frac{a}{c} \right)^2 \cos^2 \phi + \sin^2 \varphi \right]^{\frac{1}{4}}$$
(7)

$$f_{w} = \left[\sec\left(\frac{\pi \cdot c}{2W}\right)^{2} \sqrt{\frac{a}{t}}\right]^{\frac{1}{2}}$$
(8)

$$g = 1 + \left[0, 1+0, 35\left(\frac{a}{t}\right)^2\right] \cdot \left(1-\sin\phi\right)^2 \tag{9}$$

The H parameter from equation (1) is given by:

$$H = H_1 + (H_2 - H_1) \cdot (\sin \phi)^p$$
(10)

where:

$$H_1 = 1 - 0.34 \left(\frac{a}{t}\right) - 0.11 \cdot \left(\frac{a}{c}\right) \cdot \left(\frac{a}{t}\right)$$
(11)

$$H_2 = 1 + G_1 \left(\frac{a}{t}\right) + G_2 \left(\frac{a}{t}\right)^2 \tag{12}$$

$$G_1 = -1,22 - 0,12 \left(\frac{a}{c}\right)$$
(13)

$$G_2 = 0.55 - 1.05 \left(\frac{a}{c}\right)^{0.75} + 0.47 \left(\frac{a}{c}\right)^{1.5}$$
(14)

$$p = 0,2 + \left(\frac{a}{c}\right) + 0,6\left(\frac{a}{t}\right) \tag{15}$$

Values of the presented above parameters computed for one point defined on the crack front (ϕ =0) will be presented in chapter 5.

4. ASSUMPTIONS FOR THE STRESS INTENSITY FACTOR CALCULATIONS IN THE COMPRESSOR BLADE WITH THE USE OF RAJU-NEWMAN SOLUTIONS

The Raju-Newman solution for the crack in the rectangular plate is defined. The compressor blade cross-section is different from the rectangular shape. The main assumption during the preparation of this work is that the real blade cross-section is replaced with the rectangle. In this case, the Raju-Newman method [1] will be useful for the K-factor estimation in the compressor blade with the half-elliptical crack, emanated from the convex surface. The second assumption is that during the replacement, the rectangular cross-section has the same width (2W) and cross-

section area (36,45 mm²) as the blade. In further analysis, the rectangular cross-section of the blade has the following dimensions: 2W=20,48 mm (blade chord in the cross-section located 5 mm above the blade dovetail, Fig. 1b) and t=1,78 mm (Fig. 4).

The blade fracture after fatigue test is presented in Fig. 5a [7]. As seen in this figure, the crack was initiated from the convex surface of the profile, about 6 mm above the blade locking piece. The crack front shape just after the initiation is close to circular (Fig. 2). In the advanced phase of the fracture, the crack has a semi-elliptical shape (Fig 5a). The fatigue zone covers more than 95% of the blade fracture. Based on this result, it seems that the stress intensity factor in the advanced phase of the fracture was lower than critical (K_{IC}). The blade presented in Fig. 5a was vibrated with intensity of 12 g (where 1g equals 9,81 m/s²). At this intensity of excitation, the blade tip displacement amplitude after beginning of the fatigue test was about 2,5 mm.



Fig. 5. Fracture of the blade after fatigue test with distinguished selected beach marks [7] (a) and the replacing rectangular cross-section with the crack fronts defined on the basis of experimental results (b)

In this analysis, ten cracks in the rectangular plate were defined (Fig. 5b). The shape and dimensions of these cracks obtained in experimental fatigue test were determined based on the real beach marks (Fig. 5a). The K-factor will be computed only at points $1\div10$ shown in Fig 5b (for $\phi=0$).

The bending stress (σ_b) value is needed to calculate the stress intensity factor with the use of the Raju-Newman equation (1). The value of σ_b was taken from results of the FEM numerical calculations performed for the compressor blade which is vibrated with amplitude of 1 mm (Fig. 6). The maximum value of σ_z component (bending stress) in the blade cross-section equals 194 MPa. This value was used in stress intensity factor calculations for vibration amplitude of 1 mm. The area of the maximum stress is located on the convex blade surface. The minimum bending stress (-188 MPa) is located near the attack edge of the blade. The maximum value of bending stress is directly proportional to the vibration amplitude. For example, the bending stress for vibration amplitude A= 2 mm is computed as 194 MPa multiplied by 2.



Fig. 6. Bending stress (σ_z component) distribution in the blade cross-section located about 5 mm above the dovetail (1st mode of transverse vibration, vibration amplitude of 1 mm, right deflection of the blade)

5. STRESS INTENSITY FACTOR CALCULATIONS

The stress intensity factors for only one point on the cracks front were computed. In equations (7, 9 and 10), the ϕ value was defined as 0 during calculations. Thus, the K-factor value will be computed only at the beginning (or finishing) point of the crack front, where the crack tip touches the free surface. This direction is distinguished because the crack length (1) was measured just in this direction during experimental crack growth investigations.

Values of the geometrical parameters and also the factors used in the Raju-Newman solution (for $\phi=0$) are presented in Tables 1 and 2. Additionally, in Table 2, the values of the stress intensity factors for different crack sizes are shown. The first column of the tables (crack no.) should be associated with the crack numbered in Fig. 5b.

The stress intensity factors, computed for different vibration amplitudes (for $\phi=0$) are presented in Fig. 7. As seen in this figure, when the crack has length (l) of about 1,3 mm (crack position no. 1 in Fig. 5b) and is vibrated with amplitude of 1mm, the stress intensity factor value is about 5 MPa·m^{1/2}. In the finish phase of the fracture (at the same vibration amplitude, but for crack position no 10), the stress intensity factor is about 25 MPa·m^{1/2}. When the blade is vibrated with amplitude of 4 mm, the K-factor is about 96 MPa·m^{1/2} in the final phase of the fracture.

Table 1. Values of the geometrical parameters and the auxiliary factors used in Raju-Newman solution for the different crack size

Crack	a	2c	alc	a/t	c/w	0	м.	м.	м.	n	G	G.	H.	н.	f
no.	[mm]	[mm]	a/C	a/t	C/ W	Ŷ	1411	1412	1413	Р	U1	\mathbf{U}_2	111	112	ι _w
1	0,600	1,300	0,923	0,337	0,063	2,283	1,047	0,252	-0,136	1,325	-1,331	-0,022	0,851	0,549	0,764
2	0,860	2,500	0,688	0,483	0,122	1,790	1,068	0,462	-0,247	1,178	-1,303	0,025	0,799	0,377	0,841
3	1,070	3,800	0,563	0,601	0,186	1,568	1,079	0,626	-0,324	1,124	-1,288	0,066	0,758	0,250	0,900
4	1,220	5,000	0,488	0,685	0,244	1,448	1,086	0,754	-0,379	1,099	-1,279	0,097	0,730	0,169	0,945
5	1,400	7,000	0,400	0,787	0,342	1,323	1,094	0,943	-0,452	1,072	-1,268	0,141	0,698	0,090	1,016
6	1,470	8,000	0,368	0,826	0,391	1,281	1,097	1,028	-0,483	1,063	-1,264	0,159	0,686	0,065	1,054
7	1,540	9,000	0,342	0,865	0,439	1,250	1,099	1,101	-0,507	1,061	-1,261	0,174	0,673	0,039	1,098
8	1,590	10,000	0,318	0,893	0,488	1,221	1,101	1,178	-0,532	1,054	-1,258	0,190	0,665	0,027	1,146
9	1,710	13,000	0,263	0,961	0,635	1,162	1,106	1,382	-0,586	1,039	-1,252	0,228	0,646	0,008	1,343
10	1,780	17,000	0,209	1,000	0,830	1,111	1,111	1,634	-0,614	1,009	-1,245	0,270	0,637	0,025	1,945

Crack no.	f φ(φ=0)	g (\$=0)	F	H (φ=0)	$K_{I} (\phi=0)$ (A=1mm) Mpa ^x m ^{1/2}	$K_{I} (\phi=0)$ (A=2mm) Mpa ^x m ^{1/2}	$K_{I} (\phi=0)$ (A=3mm) Mpa ^x m ^{1/2}	$K_{I} (\phi=0)$ (A=4mm) Mpa ^x m ^{1/2}
1	0,961	1,140	0,898	0,851	4,264	8,528	12,792	17,056
2	0,829	1,182	0,959	0,799	5,778	11,556	17,334	23,112
3	0,750	1,226	1,046	0,758	7,130	14,260	21,390	28,520
4	0,699	1,264	1,132	0,730	8,254	16,507	24,761	33,015
5	0,632	1,317	1,272	0,698	9,940	19,880	29,820	39,761
6	0,606	1,339	1,346	0,686	10,762	21,524	32,286	43,048
7	0,585	1,362	1,434	0,673	11,664	23,328	34,991	46,655
8	0,564	1,379	1,517	0,665	12,526	25,053	37,579	50,105
9	0,513	1,423	1,846	0,646	15,727	31,455	47,182	62,910
10	0,458	1,450	2,750	0,637	24,122	48,245	72,367	96,489

Table 2. Values of the f_{ϕ} g, F, H parameters and stress intensity factor values for the blade vibrated with different amplitude



Fig. 7. Value of the stress intensity factors (for direction $\phi=0$) for different blade vibration amplitude

6. CRACK GROWTH ANALYSIS

The stress intensity factor is the main parameter during an analytical or numerical crack growth analysis. According to the Paris-Erdogan equation [8, 9], the crack growth rate can be computed from the following formula:

$$\frac{dl}{dN} = C \cdot \left(\Delta K\right)^m \tag{16}$$

where:

dl/dN - the crack growth rate (growth of the crack after one fatigue cycle);

C, m - the Paris constants

Value of ΔK is computed from equation:

$$\Delta K = K_{\max} - K_{\min} \tag{17}$$

where:

K_{max} - maximum value of K-factor in one fatigue cycle,

K_{min} - minimum value of K-factor in the fatigue cycle.

In the presented analysis, the following material constants for the EI-961 alloy were defined: $C = 1,27 \times 10^{-11}$ m/cycle and m = 3 [8, 9].

The dl and dN parameters in the Paris-Erdogan solution can be written in the finite (increment) form:

$$\frac{\Delta l}{\Delta N} = C \cdot \left(\Delta K\right)^m \tag{18}$$

where:

 $\Delta l = l_2 - l_1$

l₂, l₁ the cracks length between adjacent increments

 ΔN - number of cycles which is needed for growth of the crack from size l_1 to l_2

After transformation of equation (18), the partial number of cycles ΔN for growth of the crack from size l_1 to l_2 can be expressed as follows:

$$\Delta N = \frac{\Delta l}{C \cdot \left(\Delta K\right)^m} \tag{19}$$

The total number of cycles is computed by summing the partial (ΔN) numbers of cycles:

$$N = \sum_{i=1}^{n} \Delta N \tag{20}$$

where: n – number of increment (crack number in Tab. 3)

The values of the partial (ΔN) and total (N) number of fatigue cycles for the blade vibrating at different amplitudes are shown in Tab. 3. The ΔN and N values were computed using equations (19) and (20).

Table 3. Values of the partial (ΔN) and total (N) number of fatigue cycles for the blade vibrating at different amplitudes

Crack	a	1=2c	Δ1	ΔN	N	ΔN	N	ΔN	N	ΔN	N
no.				for	for	for	for	for	for	for	for
	[mm]	[mm]	[mm]	A=1mm	A=1mm	A=2mm	A=2mm	A=3mm	A=3mm	A=4mm	A=4mm
				Partial no.	Total no. of	Partial no.	Total no of	Partial no.	Total no.	Partial no.	Total no.
				of cycles	cycles	of cycles	cycles	of cycles	of cycles	of cycles	of cycles
1	0,60	1,3	1,3	1320289	1320289	165036	165036	48900	48900	20630	20630
2	0,86	2,5	1,2	489816	1810104	61227	226263	18141	67041	7653	28283
3	1,07	3,8	1,3	282415	2092519	35302	261565	10460	77501	4413	32696
4	1,22	5,0	1,2	168050	2260569	21006	282571	6224	83725	2626	35321
5	1,40	7,0	2,0	160342	2420911	20043	302614	5939	89663	2505	37827
6	1,47	8,0	1,0	63169	2484080	7896	310510	2340	92003	987	38814
7	1,54	9,0	1,0	49623	2533703	6203	316713	1838	93841	775	39589
8	1,59	10,0	1,0	40061	2573764	5008	321720	1484	95325	626	40215
9	1,71	13,0	3,0	60722	2634486	7590	329311	2249	97574	949	41164
10	1,78	17,0	4,0	22439	2656925	2805	332116	831	98405	351	41514

The crack growth rate for different amplitudes of vibration, computed according to formula (20) is presented in Fig. 8. In order to improve the visibility of the obtained results, the crack growth plots begin from the increment defined for the crack length equal 1,3 mm (crack length range of 0 - 1,3 mm was neglected in the plots).

Figure 8 shows that the blade vibrating at constant amplitude of 4 mm needs about $2,2 \times 10^4$ cycles to grow from size l=1,3mm to 17 mm. In the first phase of fatigue (first 10000 cycles), the crack propagates relatively slowly. After about 1×10^4 cycles, the accelerated crack growth is observed. When the vibration amplitude is smaller (i.e. 2mm), the crack propagation process is considerably longer (1,67 ×10⁵ cycles).



Fig. 8. Crack growth rate computed based on the Paris equation for crack tip position $\phi=0$ and for different vibration amplitudes

In Fig. 9 the comparison between the numerical and experimental crack growth rate for the compressor blade is presented. The experimental crack growth curve was obtained in the test, in which the intensity of vibration (excitation) equaled 7g. For this excitation intensity, the blade tip amplitude of 2 mm was observed. The blade during experimental investigations was gradually damaged. During cracking, the bending stiffness of the blade decreased. As a result, the resonant frequency of the blade also decreased. In order to maintain the constant blade amplitude during the fatigue test, the excitation frequency and the vibration intensity were changed.



Fig. 9. Comparison of the numerical and experimental crack growth rates for the compressor blade vibrating with amplitude of 2 mm

As seen in Fig. 9, the crack in the blade achieved length of 4 mm after about $2,6 \times 10^5$ cycles (computed based on the Raju-Newman and Paris solutions). During the experimental fatigue test, the 4 mm crack was detected after about $3,7 \times 10^5$ cycles. Thus, the difference between the numerical and experimental results is about $1,1 \times 10^5$ cycles. It gives the relative error of about 30%. For the crack size of 10 mm, the experimental curve has a lower slope than the analytical one, and, in consequence, the error at this stage of fracture is slightly bigger (33%). In the final phase of fracture (for l=17 mm), the number of cycles estimated in the analytical way is about $3,8 \times 10^5$, while the experimental result is $4,9 \times 10^5$ cycles.

In the comparison described below, the partial number of cycles computed from the Paris equation in the first increment (0-1,3 mm) was also included. However, the consideration of this increment in the comparison of analytical and experimental results is controversial because the Paris equation describes correctly only the stable phase of the crack growth. After the omission of the first increment, the difference between the analytical and numerical solution is much smaller.

7. CONCLUSIONS

In this study, the stress intensity factor for the 1st stage compressor blade was computed. In this analysis, the Raju-Newman analytical solution was used. A half-elliptical surface crack was embedded in the analyzed blade. The location of this crack and the crack front shape were defined based on the experimental results obtained for the blade tested in resonance conditions. The K-factor values were computed only at one point of the crack front, where the crack tip touches the free surface as the crack length (1) was measured just in this direction (ϕ =0) during experimental investigations. In order to determine the stress intensity factors for different crack sizes, ten diverse flaws in the blade were defined.

In the next part of this work, the stress intensity factor values were used as an input data into the Paris-Erdogan equation. As a result of this calculation, the crack growth rate for the compressor blade vibrating at constant amplitude was estimated. The obtained results were finally compared with the results of the experimental crack growth analysis performed for 1st stage compressor blades of the helicopter turbo-engine.

The results obtained in the analytical way are conservative (from the engineering point of view). The analytical estimation using the Raju-Newman and Paris equations gives the fatigue cycle values which are about 30% lower than those obtained in the experimental tests. This divergence could be caused by inaccurate definitions of C and m constants in the Paris equation. Moreover, the replacement of the real blade cross-section with the rectangular shape has a certain influence on the accuracy of the analytical solution. After the omission of the first increment (concerning crack growth from initiation to length l=1,3 mm), the difference between the analytical and numerical solution is much smaller.

The author's intention is to calculate (in the next study) the stress intensity factor in the compressor blade using the hybrid method. In this approach, the finite element method will be used for stress analysis. Subsequently, the boundary element method will be utilized for the crack definition and also for the stress intensity factor calculation. The obtained numerical results can be compared with the K-factor values computed from the Raju-Newman solution.

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