



## Positive solutions for semilinear elliptic systems with sign-changing potentials

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### Abstract

In this paper, we study the existence of positive solutions of the Dirichlet problem  $-\Delta u = \lambda p(x)f(u, v)$ ;  $-\Delta v = \lambda q(x)g(u, v)$ , in  $D$ , and  $u = v = 0$  on  $\partial^\infty D$ , where  $D \subset \mathbb{R}^n$  ( $n \geq 3$ ) is an  $C^{1,1}$ -domain with compact boundary and  $\lambda > 0$ . The potential functions  $p, q$  are not necessarily bounded, may change sign and the functions  $f, g : \mathbb{R}^2 \rightarrow \mathbb{R}$  are continuous with  $f(0, 0) > 0$ ,  $g(0, 0) > 0$ . By applying the Leray-Schauder fixed point theorem, we establish the existence of positive solutions for  $\lambda$  sufficiently small.

### 1 Introduction

Let  $D$  be a  $C^{1,1}$  domain of  $\mathbb{R}^n$  ( $n \geq 3$ ) with compact boundary and let  $\partial^\infty D = \partial D$  if  $D$  is bounded and  $\partial^\infty D = \partial D \cup \{\infty\}$  whenever  $D$  is unbounded. This paper deals with the existence of positive continuous solutions (in the sense of distributions) for the following semilinear elliptic system

$$\begin{cases} -\Delta u = \lambda p(x)f(u, v), & \text{in } D, \\ -\Delta v = \lambda q(x)g(u, v), & \text{in } D, \\ u = v = 0 & \text{on } \partial^\infty D, \end{cases} \quad (1.1)$$

where the potential functions  $p, q$  are sign changing functions belonging to the Kato class  $K(D)$  introduced and studied in [1] and [9] and  $f, g$  satisfy the following hypothesis.

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(**H<sub>1</sub>**) The functions  $f, g : \mathbb{R}^2 \rightarrow \mathbb{R}$  are continuous with  $f(0,0) > 0$  and  $g(0,0) > 0$ .

In recent years, a good amount of research is established for reaction-diffusion systems. reaction-diffusions systems model many phenomena in Biology, Ecology, combustion theory, chemical reactors, population dynamics etc. And the case  $p(x) = q(x) = 1$  has been considered as a typical example when  $D$  is a bounded regular domain in  $\mathbb{R}^n$  and many existence results were established by variational methods, topological methods and the method of sub and supersolution (see [5], [7], [4]).

Recently, Chen [2] studied the existence of positive solutions for the following system

$$\begin{cases} -\Delta u = \lambda p(x)f_1(v), & \text{in } D, \\ -\Delta v = \lambda q(x)g_1(v), & \text{in } D, \\ u = v = 0 & \text{on } \partial^\infty D, \end{cases} \quad (1.2)$$

where  $D$  is a bounded domain. He assumed that if  $p, q$  are continuous in  $\overline{D}$  and

(**H<sub>2</sub>**) There exists  $\mu_1, \mu_2 > 0$  such that

$$\begin{aligned} \int_D G(x,y)p_+(y) dy &> (1 + \mu_1) \int_D G(x,y)p_-(y) dy \quad \forall x \in D, \\ \int_D G(x,y)q_+(y) dy &> (1 + \mu_2) \int_D G(x,y)q_-(y) dy \quad \forall x \in D, \end{aligned}$$

where  $G(x,y)$  is the Green's function of the Dirichlet Laplacian in  $D$ . Here  $p^+, q^+$  are the positive parts of  $p$  and  $q$ , while  $p_-, q_-$  are the negative ones.

The main result of Chen [2] reads as follows.

**Theorem A.** Let  $p, q$  be nonzero continuous functions on  $\overline{D}$  satisfying **H<sub>2</sub>** and let  $f_1, g_1 : [0, \infty) \rightarrow \mathbb{R}$  be continuous with  $f_1(0) > 0, g_1(0) > 0$ . Then there exists a positive number  $\lambda^* > 0$  such that (1.2) has a positive solution for  $0 < \lambda < \lambda^*$ .

We note that in the case where  $f_1, g_1$  are nonnegative nondecreasing continuous functions,  $p(x) \leq 0$  in  $D$  and  $q(x) \leq 0$  in  $D$ , system (1.2) was studied in [6] with nontrivial nonnegative boundary data and the existence of positive bounded solutions for (1.2) was established whenever  $\lambda$  is a small positive real number.

Our aim in this paper is to extend and improve, by a modified proof, the result of Chen [2] in a number of ways. First, the domain  $D$  will be bounded or an exterior domain. Second, the functions  $p, q$  are not necessarily continuous in  $\overline{D}$ .

Indeed  $p, q$  may be singular on the boundary of  $D$ . Third, the nonlinear terms  $f_1(v)$  and  $g_1(u)$  considered in [2] are more restrictive than the class  $f(u, v)$  and  $g(u, v)$  considered in our case. More precisely, we will establish the existence of a positive solution for (1.1) in the case where  $f(0, 0) > 0$ ,  $g(0, 0) > 0$  and the potentials of  $p, q$  satisfy hypothesis **(H<sub>2</sub>)** and belong to the Kato class introduced and studied in [1] and [9]. A nonexistence of positive bounded solution will be also given in the case where  $f$  and  $g$  are sublinear functions with  $f(0, 0) = 0$  and  $g(0, 0) = 0$ . To this aim, we give in the sequel some notations and we recall some properties of the Kato class.

**Definition 1.1.** (See [1] and [9].) A Borel measurable function  $k$  in  $D$  belongs to the Kato class  $K(D)$  if

$$\lim_{\alpha \rightarrow 0} \sup_{x \in D} \int_{D \cap B(x, \alpha)} \frac{\rho(y)}{\rho(x)} G(x, y) |k(y)| dy = 0$$

and satisfies further

$$\lim_{M \rightarrow \infty} \sup_{x \in D} \int_{D \cap \{|y| \geq M\}} \frac{\rho(y)}{\rho(x)} G(x, y) |k(y)| dy = 0 \quad (\text{ whenever } D \text{ is unbounded}),$$

where  $\rho(x) = \min(1, \delta(x))$  and  $\delta(x)$  denotes the euclidian distance from  $x$  to the boundary of  $D$ .

We remark that in the case where  $D$  is bounded and if  $d$  denotes its diameter, then

$$\frac{1}{1+d} \delta(x) \leq \rho(x) \leq \delta(x).$$

So in this case, we can replace  $\rho(x)$  by  $\delta(x)$  in the Definition 1.1.

Next, we give some examples of functions belonging to  $K(D)$ .

**Example 1.1.** (see [1] and [9])

(1) Let  $D$  be a bounded domain of  $\mathbb{R}^n$ .

(a) Let  $q(y) = \frac{1}{(\delta(y))^\lambda}$ . Then  $q \in K(D)$  if and only if  $\lambda < 2$ .

(b) Let  $p > \frac{n}{2}$ , then for  $\lambda < 2 - \frac{n}{p}$ , we have  $\frac{1}{\delta(\cdot)^\lambda} L^p(D) \subset K(D)$ . In particular  $L^p(D) \subset K(D)$ .

(c) Let  $D = B(0, 1)$  and let  $q$  be a Borel radial function in  $D$ , then  $q \in K(D)$  if and only if  $\int_0^1 r(1-r)|q(r)| dr < \infty$ .

(2) Let  $D$  be a  $C^{1,1}$ -exterior domain in  $\mathbb{R}^n$  ( $n \geq 3$ ). The function  $x \rightarrow \frac{1}{(|x|+1)^{\mu-\lambda} \delta(x)^\lambda} \in K(D)$  if and only if  $\lambda < 2 < \mu$ .

- (3) Let  $D = \overline{B(0,1)}^c$  be the exterior of the unit closed ball in  $\mathbb{R}^n$  ( $n \geq 3$ ) and let  $q$  be a Borel radial function in  $D$ , then  $q \in K(D)$  if and only if  $\int_1^\infty (r-1)|q(r)|dr < \infty$ .

For any nonnegative Borel measurable function  $\varphi$  in  $D$ , we denote by  $V\varphi$  the Green potential of  $\varphi$  defined on  $D$  by

$$V\varphi(x) = \int_D G(x,y)\varphi(y)dy.$$

Recall that if  $\varphi \in L^1_{loc}(D)$  and  $V\varphi \in L^1_{loc}(D)$ , then we have in the distributional sense (see [3] p. 52)

$$\Delta(V\varphi) = -\varphi \text{ in } D. \quad (1.3)$$

Our main results are as follows.

**Theorem 1.2.** *Let  $p, q$  be in the Kato class  $K(D)$  and assume that hypotheses  $(H_1) - (H_2)$  are satisfied. Then there exists  $\lambda_0 > 0$  such that for each  $\lambda \in (0, \lambda_0)$ , problem (1.1) has a positive continuous solution in  $D$ .*

For the nonexistence of positive bounded solutions, we establish

**Theorem 1.3.** *Let  $p, q$  be two nontrivial functions in the Kato class  $K(D)$ . Assume that the functions  $f, g : \mathbb{R}^2 \rightarrow \mathbb{R}$  are measurable and there exists a positive constant  $M$  such that for all  $u, v$  we have,*

$$\begin{aligned} |f(u, v)| &\leq M(|u| + |v|) \\ |g(u, v)| &\leq M(|u| + |v|). \end{aligned}$$

*Then there exists  $\lambda_0 > 0$  such that the problem (1.1) has no bounded positive continuous solution in  $D$  for each  $\lambda \in (0, \lambda_0)$ .*

Throughout this paper, we denote by  $B(D)$  the set of Borel measurable functions in  $D$  and by  $C_0(D)$  the set of continuous ones satisfying

$$\lim_{x \rightarrow \xi \in \partial^\infty D} u(x) = 0.$$

Finally, for a bounded real function  $\omega$  defined on a set  $S$  we denote by  $\|\omega\|_\infty = \sup_{x \in S} |\omega(x)|$ .

## 2 Proof of Theorems 1.2 and 1.3

We begin this section by giving a continuity result.

**Proposition 2.1.** *(see [1] and [9]) Let  $\varphi$  be a nonnegative function in  $K(D)$ . Then we have*

- i) The function  $y \rightarrow \frac{\delta(y)}{(1+|y|)^{n-1}}\varphi(y)$  is in  $L^1(D)$ . In particular  $\varphi \in L^1_{loc}(D)$ .
- ii)  $V\varphi \in C_0(D)$ .
- iii) Let  $h_0$  be a positive harmonic function in  $D$  which is continuous and bounded in  $\bar{D}$ . Then the family of functions

$$\left\{ \int_D G_{\cdot, y} h_0(y) p(y) dy : |p| \leq \varphi \right\}$$

is relatively compact in  $C_0(D)$ .

Next, we recall first the Leray-Schauder fixed point theorem.

**Lemma 2.2.** (Leray-Schauder fixed point theorem) *Let  $X$  be a Banach space with norm  $\|\cdot\|$  and  $x_0$  be a point of  $X$ . Suppose that  $T : X \times [0, 1] \rightarrow X$  is continuous and compact with  $T(x, 0) = x_0$ , for each  $x \in X$ , and there exists a fixed constant  $M > 0$  such that each solution  $(x, \sigma) \in X \times [0, 1]$  of the  $T(x, \sigma) = x$  satisfies  $\|x\| \leq M$ . Then  $T(\cdot, 1)$  has a fixed point.*

Using this Lemma, we obtain the following general existence result.

**Lemma 2.3.** *Suppose that  $p$  and  $q$  are in the Kato class  $K(D)$  and  $f, g$  are continuous and bounded from  $\mathbb{R}^2$  to  $\mathbb{R}$ . Then for every  $\lambda \in (0, \infty)$ , problem (1.1) has a solution  $(u_\lambda, v_\lambda) \in C_0(D) \times C_0(D)$ .*

**Proof.** For  $\lambda \in \mathbb{R}$ , we consider the operator  $T_\lambda : C_0(D) \times C_0(D) \times [0, 1] \rightarrow C_0(D) \times C_0(D)$  defined by

$$T_\lambda((u, v), \sigma) = (\sigma \lambda V(pf(u, v)), \sigma \lambda V(qg(u, v))).$$

By Proposition 2.1, the operator  $T_\lambda$  is well defined, continuous, compact and  $T_\lambda((u, v), 0) = (0, 0) := x_0 \in C_0(D) \times C_0(D)$ . Let  $(u, v) \in C_0(D) \times C_0(D)$  and  $\sigma \in [0, 1]$  such that  $T_\lambda((u, v), \sigma) = (u, v)$ . Then, since  $f, g$  are bounded and  $p, q$  are in  $K(D)$  we deduce by using Proposition 2.1 that

$$\begin{aligned} \max(\|u\|_\infty, \|v\|_\infty) &= \sigma \lambda \max(\|V(pf(u, v))\|_\infty, \|V(qg(u, v))\|_\infty) \\ &\leq \lambda \max(\|Vp\|_\infty \|f\|_\infty, \|Vq\|_\infty \|g\|_\infty) \\ &= M. \end{aligned}$$

Hence by Leray-Schauder fixed point theorem, the operator  $T_\lambda(\cdot, 1)$  has a fixed point. Namely, there exists  $(u, v) \in C_0(D) \times C_0(D)$  such that  $(u, v) = (\lambda V(pf(u, v)), \lambda V(qg(u, v)))$ . So, using (1.3) and Proposition 2.1, we deduce that  $(u, v)$  is a solution of system (1.1).

**Proof of Theorem 1.2.** Fix a large number  $M > 0$  and an infinitely continuously differentiable function  $\psi$  with compact support on  $\mathbb{R}^2$  such that  $\psi = 1$  in the open ball with center 0 and radius  $M$  and  $\psi = 0$  on the exterior of the ball with center 0 and radius  $2M$ . Define the bounded functions  $\tilde{f}, \tilde{g}$  on  $\mathbb{R}^2$  by  $\tilde{f}(u, v) = \psi(u, v)f(u, v)$  and  $\tilde{g}(u, v) = \psi(u, v)g(u, v)$ . By Lemma 2.3, the Dirichlet problem:

$$\begin{cases} -\Delta u = \lambda p(x)\tilde{f}(u, v), & \text{in } D, \\ -\Delta v = \lambda q(x)\tilde{g}(u, v), & \text{in } D, \\ u = v = 0 & \text{on } \partial^\infty D, \end{cases} \quad (2.1)$$

has a solution  $(u_\lambda, v_\lambda) \in C_0(D) \times C_0(D)$  satisfying

$$(u_\lambda, v_\lambda) = (\lambda V(p\tilde{f}(u_\lambda, v_\lambda))\lambda V(q\tilde{g}(u_\lambda, v_\lambda))).$$

Moreover

$$\max(\|u_\lambda\|_\infty, \|v_\lambda\|_\infty) \leq \lambda \max(\|Vp\|_\infty \|\tilde{f}\|_\infty, \|Vq\|_\infty \|\tilde{g}\|_\infty) \quad (2.2)$$

Put  $\mu = \min(\mu_1, \mu_2)$  and consider  $\gamma \in (0, \frac{\mu}{2+\mu})$ . Since  $\tilde{f}$  and  $\tilde{g}$  are continuous, then there exists  $\delta \in (0, M)$  such that if  $\max(|\zeta|, |\xi|) < \delta$ , we have  $\tilde{f}(0, 0)(1 - \gamma) < \tilde{f}(\zeta, \xi) < \tilde{f}(0, 0)(1 + \gamma)$  and  $\tilde{g}(0, 0)(1 - \gamma) < \tilde{g}(\zeta, \xi) < \tilde{g}(0, 0)(1 + \gamma)$ . Using (2.2), we deduce that there exists  $\lambda_0 > 0$  such that  $\|u_\lambda\|_\infty < \delta$  and  $\|v_\lambda\|_\infty < \delta$  for any  $\lambda \in (0, \lambda_0)$ . This together with the fact that  $0 < \delta < M$  implies that for  $\lambda \in (0, \lambda_0)$ , we have  $\tilde{f}(u_\lambda, v_\lambda) = f(u_\lambda, v_\lambda)$  and  $\tilde{g}(u_\lambda, v_\lambda) = g(u_\lambda, v_\lambda)$ .

Now, for each  $x \in D$  we have

$$\begin{aligned} u_\lambda &= \lambda V(p_+\tilde{f}(u_\lambda, v_\lambda)) - \lambda V(p_-\tilde{f}(u_\lambda, v_\lambda)) \\ &> \lambda f(0, 0)(1 - \gamma)V(p_+) - \lambda f(0, 0)(1 + \gamma)V(p_-) \\ &> \lambda f(0, 0)[(1 - \gamma)(1 + \mu_1) - (1 + \gamma)]V(p_-) \\ &> \lambda f(0, 0)(1 - \gamma) \left[ 1 + \mu_1 - \frac{1 + \gamma}{1 - \gamma} \right] V(p_-) \\ &> \lambda f(0, 0)(1 - \gamma) \left[ 1 + \mu - \frac{1 + \gamma}{1 - \gamma} \right] V(p_-). \end{aligned}$$

Now, since  $\gamma \in (0, \frac{\mu}{2+\mu})$ , then  $1 + \mu - \frac{1 + \gamma}{1 - \gamma} > 0$  and it follows that

$\lambda f(0, 0)(1 - \gamma) \left[ 1 + \mu - \frac{1 + \gamma}{1 - \gamma} \right] V(p_-) \geq 0$ . Consequently, for each  $\lambda \in (0, \lambda_0)$  and for each  $x \in D$  we have  $u_\lambda(x) > 0$ . Similarly, we obtain  $v_\lambda(x) > 0$  for each  $x \in D$ .

**Proof of Theorem 1.3** Suppose that (1.1) has a bounded positive solution  $(u, v)$  for  $\lambda > 0$ . Then  $f(u, v)$  and  $g(u, v)$  are bounded. Put  $\tilde{u} = \lambda V(p f(u, v))$  and  $\tilde{v} = \lambda V(q g(u, v))$ . Since  $f(u, v)$  and  $g(u, v)$  are bounded, then the functions  $\tilde{u}, \tilde{v} \in C_0(D)$ . The functions  $z = u - \tilde{u}$  and  $\omega = v - \tilde{v}$  are harmonic in the distributional sense and continuous in  $D$ , so they are harmonic in the classical sense. Moreover, since  $u = \tilde{u} = v = \tilde{v} = 0$  on  $\partial^\infty D$  then  $u = \tilde{u}$  and  $v = \tilde{v}$  in  $D$ . Which implies

$$\begin{aligned} \|u\|_\infty &\leq \lambda V(|p|f(u, v)) \leq \lambda M \|V(|p|)\|_\infty (\|u\|_\infty + \|v\|_\infty), \\ \|v\|_\infty &\leq \lambda V(|q|g(u, v)) \leq \lambda M \|V(|q|)\|_\infty (\|u\|_\infty + \|v\|_\infty). \end{aligned}$$

By adding these inequalities, we obtain

$$(\|u\|_\infty + \|v\|_\infty) \leq \lambda M [\|V(|p|)\|_\infty + \|V(|q|)\|_\infty] (\|u\|_\infty + \|v\|_\infty).$$

This gives a contradiction if  $\lambda M [\|V(|p|)\|_\infty + \|V(|q|)\|_\infty] < 1$ .

**Example 2.1.** Let  $p, q$  be two measurable radial functions on the exterior of the unit ball  $D = \overline{B(0, 1)}^c$ ,  $n \geq 3$ . Assume that there exists  $\varepsilon > 0$  such that each  $t > 1$  and  $x \in D$ , we have

$$\begin{aligned} &\int_1^t \frac{r^{n-1}}{(|x| \vee r)^{n-2}} (1 - (|x| \wedge r)^{2-n}) p^+(r) dr \\ &\quad \geq (1 + \varepsilon) \int_1^t \frac{r^{n-1}}{(|x| \vee r)^{n-2}} (1 - (|x| \wedge r)^{2-n}) p^-(r) dr, \quad \text{and} \\ &\int_1^t \frac{r^{n-1}}{(|x| \vee r)^{n-2}} (1 - (|x| \wedge r)^{2-n}) q^+(r) dr \\ &\quad \geq (1 + \varepsilon) \int_1^t \frac{r^{n-1}}{(|x| \vee r)^{n-2}} (1 - (|x| \wedge r)^{2-n}) q^-(r) dr, \end{aligned}$$

then hypothesis **(H<sub>2</sub>)** is satisfied. Indeed (see [1]), for a nonnegative radial function  $k$ , the function  $x \rightarrow \int_D G_D(x, y) k(|y|) dy$  is radial and

$$\int_D G_D(x, y) k(|y|) dy = a_n \int_1^\infty \frac{r^{n-1}}{(|x| \vee r)^{n-2}} (1 - (|x| \wedge r)^{2-n}) k(r) dr,$$

where  $|x| \wedge t = \min(|x|, t)$ ,  $|x| \vee t = \max(|x|, t)$  and  $a_n > 0$ .

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